

On counterfactual inference in factor models with nearest neighbors



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Factor models, sequential experiments, nearest neighbors

Panel data: N users with a series of treatments over T time points, where for user $i \in [N]$, at time $t \in [T]$, we observe outcome $Y_{i,t}$ that depends on the assigned treatment $A_{i,t}$, the potential outcomes $\{\theta_{i,t}^{(a)}\}$ for $a \in \mathcal{A}$, and noise $\epsilon_{i,t}$. **Our goal** is counterfactual inference with **latent factor model**, i.e., estimate $\{\theta_{i,t}^{(a)}\}$ with user x time-level guarantee

$$Y_{i,t} = \theta_{i,t}^{(A_{i,t})} + \epsilon_{i,t} \quad A_{i,t} \sim \text{policy}_{i,t}$$

$$\theta_{i,t}^{(a)} = \langle u_i^{(a)}, v_t^{(a)} \rangle$$

User-based nearest neighbors (User-NN):

Find NN users $\mathcal{N}_i^{(a)} = \{j : \rho_{i,j}^{(a)} \leq \eta\}$ and average

(choosing $a=1$ for simpler notation)

$$\rho_{i,j}^{(1)} = \frac{\sum_{t'=1}^T A_{i,t'} A_{j,t'} (Y_{i,t'} - Y_{j,t'})^2}{\sum_{t'=1}^T A_{i,t'} A_{j,t'}}$$

$$\hat{\theta}_{i,t,\text{user}}^{(1)} = \frac{\sum_{j \in \mathcal{N}_i^{(1)}} A_{j,t} Y_{j,t}}{\sum_{j \in \mathcal{N}_i^{(1)}} A_{j,t}}$$

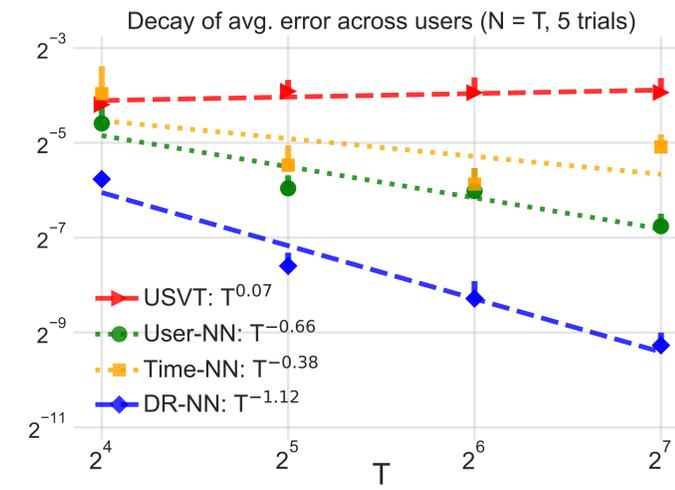
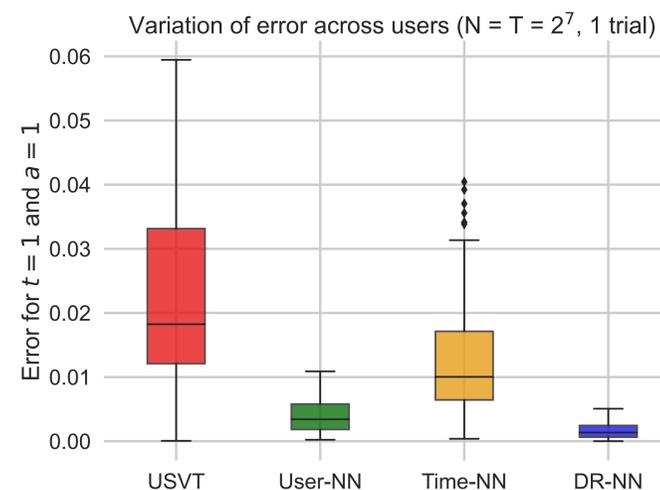
For **sequentially adaptive policies**, with suitable η , and regularity conditions with high probability (whp)

$$(\hat{\theta}_{i,t,\text{user}}^{(a)} - \theta_{i,t}^{(a)})^2 \lesssim \frac{1}{\sqrt{T}} + \frac{M}{N}$$

with M distinct types of users

Simulation results with pooled ϵ -greedy treatment policy

- Latent factors uniform on $[-0.5, 0.5]^2$, avg. treatment effect = 0, noise-var = $1e-4$
- Pooled ϵ -greedy treatment policy with $\epsilon = 0.5$
- Methods: USVT [Chatterjee '15], User-NN, Time-NN, DR-NN, results for a single time point



A "doubly robust" approach for nearest neighbors

$$|u^* v^* - \hat{u} \hat{v}| \leq |v^*| |\hat{u} - u^*| + |\hat{u}| |\hat{v} - v^*|$$

$$= O(|\hat{u} - u^*| + |\hat{v} - v^*|)$$

Panel data: $u^* = u_i, v^* = v_t$
(dropping 'a' in notation)

User NN: $\hat{u} = \frac{\sum_{j \in \mathcal{N}_i} u_j}{|\mathcal{N}_i|}, \hat{v} = v_t$

Time NN: $\hat{u} = u_i, \hat{v} = \frac{\sum_{t' \in \mathcal{T}_t} v_{t'}}{|\mathcal{T}_t|}$

Motivating question:

$$|u^* v^* - ??| = O(|\hat{u} - u^*| \times |\hat{v} - v^*|)$$

$$u^* v^* - ?? = (\hat{u} - u^*) \times (\hat{v} - v^*)$$

$$= \hat{u} \hat{v} - u^* \hat{v} - \hat{u} v^* + u^* v^*$$

$$\implies ?? = u^* \hat{v} + \hat{u} v^* - \hat{u} \hat{v}$$

Doubly robust (DR) NN

$$\hat{\theta}_{i,t,\text{DR}}^{(1)} = \frac{\sum_{j \in \mathcal{N}_i^{(1)}, t' \in \mathcal{T}_t} A_{j,t} A_{i,t'} A_{j,t'} (Y_{j,t} + Y_{i,t'} - Y_{j,t'})}{\sum_{j \in \mathcal{N}_i^{(1)}, t' \in \mathcal{T}_t} A_{j,t} A_{i,t'} A_{j,t'}}$$

Guarantee: For non-adaptive policies, with suitable hyper-parameters and regularity conditions, w.h.p.,

$$(\hat{\theta}_{i,t,\text{DR}}^{(a)} - \theta_{i,t}^{(a)})^2 \lesssim \frac{M}{T} + \frac{M}{N}$$

(M distinct types of user & time latent factors)

— **a quadratic improvement.** More generally,

$$\text{Err}(\text{DR-NN}) \lesssim \min\{\text{Err}(\text{User-NN}), \text{Err}(\text{Time-NN})\}$$

HeartSteps: A mobile health study with Thompson sampling

- 3 months sequentially adaptive trial with 91 users: Mobile notifications sent ($a=1$) or not ($a=0$), 5 times a day ($T=450$) using Thompson sampling independently for each user, outcome = log of step-count in the 30-minute window after the decision time
- Results for $a = 0$ at 50 held out decision times

