# From HeartSteps to HeartBeats: <br> Personalized Decision-making 



# Personalized Decision-making 

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Driven by<br>extensive data collection,<br>decreasing cost of computation, synergy between disciplines



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Medical records


Model
Personalized Decision-making

Driven by
extensive data collection, decreasing cost of computation, synergy between disciplines

Medical records


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extensive data collection, decreasing cost of computation, synergy between disciplines


1. Use real data to infer decision's effect




2. Use simulated data to predict decision's effect

3. Use simulated data to predict decision's effect

4. Use simulated data to predict decision's effect

5. Use simulated data to predict decision's effect

6. Use simulated data to predict decision's effect


## Building AI agents for personalized treatments



## Building Al agents for personalized treatments

How to assign personalized digital treatments to help you?


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How to assign personalized digital treatments to help you?


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PTSD Coach




Insomnia
Coach


Apple Research app
The future of health research is you.

## Building AI agents for personalized treatments

How to assign personalized digital treatments to help you?

Mobile health study:
Personalized HeartSteps

- Goal: Promote physical activity via mobile app

- Population: 91 hypertension patients, 90 days


PTSD Coach


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## Mobile health study: <br> Personalized HeartSteps





Couples Coach

- Goal: Promote physical activity via mobile app
- Population: 91 hypertension patients, 90 days
- Treatment: Mobile notifications 5 times/day assigned by a bandit algorithm

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PTSD Coach

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## After-study personalized inference questions

How to assign personalized digital
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(2)Did the app increase physical activity for a given user?

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Was sending the notification effective?
Was the bandit algorithm effective?

- Challenges: Lack of mechanistic models, adaptively collected data, expensive data collection


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(3) VA Mobile Apps
image credits


## Part 1 overview: Sample-efficient personalized

 inference in sequential experimentsHow to assign personalized digital treatments to help you?

1)

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This talk
Was sending the notification effective?
Was the bandit algorithm effective?

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## VA Mobile Apps



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Sequentially adaptive policy that can pool observed data across users to speed up learning

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Y_{i, t}=\theta_{i, t}^{\left(A_{i, t}\right)}+\text { noise }_{i, t}
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[Neyman-Rubin framework

+ SUTVA]


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- Enable generic after-study analyses and assist next study design


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- Enable generic after-study analyses and assist next study design
- E.g., how effective was the notification for user $i$ at time $t\left(\theta_{i, t}^{(1)}-\theta_{i, t}^{(0)}\right)$ ?

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## Challenges:

$\Rightarrow$ More unknowns than (noisy) observations

An impossible task without structural assumptions...

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## Hope:

$\star N$ iid users
$\star T$ (dependent) observations per user
$\star$ If users are not all too different \& multiple observations can help find similarities

A possible task with some structural assumptions...

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## Prior work:

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- IID users \& deterministic rules/policies

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[... Robins '94, '97, '00, '08, Murphy '03, '05, Hernan+ '06, Moodie+ '07,

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Deshpande+'18, Hadad+ '21, Bibaut+ '21, Khamaru+ '21, Zhang+ '21

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- IID user trajectories (per user policy, no pooling)

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Prior work:

- Average treatment effect
- IID users \& deterministic rules/policies
- IID users at each time with stochastic policies
- IID user trajectories (per user policy, nc pooling)
- Observational studies (once treated forever treated; synthetic control, causal panel data)

Structural assumption: Non-parametric factor model

$$
Y_{i, t}=\theta_{i, t}^{(4, t)}+\text { noise }_{i, t}
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Structural assumption: Non-parametric factor model

$$
Y_{i, t}=\theta_{i, t}^{\left(A_{i, t}\right)}+\text { noise }_{i, t}
$$

$$
\begin{array}{cc}
\theta_{i, t}^{(a)} \stackrel{\Delta}{=} f^{(a)}\left(u_{i}^{(a)}, v_{t}^{(a)}\right) \\
\text { user factor } & \text { time factor } \\
\begin{array}{cc}
(\text { e.g., personal } & \text { (e.g., societal, weather } \\
\text { traits) } & \text { changes) }
\end{array}
\end{array}
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No parametric assumptions on

- unknown non-linearity
- distributions of unobserved
latent factors and noise


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User nearest neighbors estimator for $\theta_{i, t}^{(a)}$

$$
Y_{i t}=\theta_{i, k}^{(a, j)}+\text { noise }_{t, t}
$$

## User nearest neighbors estimator for $\theta_{i, t}^{(a)}$

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Y_{i, t}=\theta_{i, t}^{\left(A_{i, t}\right)}+\text { noise }_{i, t}
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1. Compute distance between two users $i$ and $j$ under treatment $a$

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\rho_{i, j}^{(a)}=\frac{\sum_{t^{\prime}=1}^{T}\left(Y_{i, t^{\prime}}-Y_{j, t^{\prime}}\right)^{2} \cdot \mathbf{1}\left(A_{i, t^{\prime}}=A_{j, t^{\prime}}=a\right)}{\sum_{t^{\prime}=1}^{T} \mathbf{1}\left(A_{i, t^{\prime}}=A_{j, t^{\prime}}=a\right)}
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Squared distance between outcomes averaged over all times when $i$ and $j$ are both treated with $a$
2. Average outcome across user neighbors treated with $a$ at time $t$

$$
\mathbf{1}\left(\rho_{i, j}^{(a)} \leq \eta, A_{j, t}=a\right)
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Squared distance between outcomes averaged over all times when $i$ and $j$ are both treated with $a$
2. Average outcome across user neighbors treated with $a$ at time $t$

$$
\hat{\theta}_{i, t, \text { user-NN }}^{(a)}=\frac{\sum_{j=1}^{N} Y_{j, t} \cdot \mathbf{1}\left(\rho_{i, j}^{(a)} \leq \eta, A_{j, t}=a\right)}{\sum_{j=1}^{N} \mathbf{1}\left(\rho_{i, j}^{(a)} \leq \eta, A_{j, t}=a\right)}
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Main result: A non-asymptotic guarantee for each (i, $t, a)$

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Informal theorem: [Dwivedi-Tian-Tomkins-Klasnja-Murphy-Shah '22a]
For suitably chosen $\eta$ \& under regularity conditions

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$$
\left|\hat{\theta}_{i, t, \text { user-NN }}^{(a)}-\theta_{i, t}^{(a)}\right| \lesssim \frac{1}{T^{1 / 4}}+\frac{1}{(N / M)^{1 / 2}}
$$

(Uniform on finite set of size $M$ )

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& \left|\hat{\theta}_{i, t, \text { user-NN }}^{(a)}-\theta_{i, t}^{(a)}\right| \lesssim \frac{1}{T^{1 / 4}}+\frac{1}{N^{1 /(d+2)}}
\end{aligned}
$$

User factor distribution
(Uniform on finite set of size $M$ )
(Uniform over $[-1,1]^{d}$ )
$\left(†\right.$ Our general results allow $p$ to decay as $\left.\gtrsim T^{-1 / 2}\right)$

## User-NN guarantees: Advantages

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- Asymptotic confidence intervals as $N, T \rightarrow \infty$ :

$$
\widehat{\theta}_{i, t, \text { user-NN }}^{(a)} \pm \frac{1.96 \hat{\sigma}}{\sqrt{\#_{\text {neighbors }}^{i, t, a}}}
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Confidence intervals for treatment effect $\theta_{i, t}^{(1)}-\theta_{i, t}^{(0)}$

Challenges tackled: First guarantee for user-time-level counterfactuals
$\checkmark$ More unknowns than observations
$\checkmark$ Non-parametric model
$\checkmark$ Heterogeneity across users \& time $\checkmark$ Generic sequential policies

## User-NN guarantees: Advantages

- Asymptotic confidence intervals as $N, T \rightarrow \infty$ :

- $\left|\hat{\theta}_{i, t \text { user-NN }}^{(a)}-\theta_{i, t}^{(a)}\right|=\tilde{O}\left(\frac{1}{T^{1 / 4}}+\frac{1}{\sqrt{N}}\right)$

Challenges tackled: First guarantee for user-time-level counterfactuals
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## User-NN guarantees: Advantages

Challenges tackled: First guarantee

- Asymptotic confidence intervalls as $N, T \rightarrow \infty$ : for user-time-level counterfactuals

- $\left|\widehat{\theta}_{i, t, \text { user-NN }}^{(a)}-\theta_{i, t}^{(a)}\right|=\tilde{O}\left(\frac{1}{T^{1 / 4}}+\frac{1}{\sqrt{N}}\right)$
$\checkmark$ More unknowns than observations
$\sqrt{ }$ Non-parametric model
$\checkmark$ Heterogeneity across users \& time
$\checkmark$ Generic sequential policies


$$
\text { ?? }-\theta_{i, t}^{(a)} \left\lvert\,=\tilde{O}\left(\frac{1}{\sqrt{T}}+\frac{1}{\sqrt{N}}\right)\right. \text { Can we improve the slow rate in T? }
$$

## Yes, we can!

A near-quadratic improvement over user-NN

## Yes, we can!

## A near-quadratic improvement over user-NN

Informal theorem: [Dwivedi-Tian-Tomkins-Klasnja-Murphy-Shah '22b]
A suitable variant of nearest neighbors improves* upon the user-NN error

$$
\begin{aligned}
& \left|\hat{\theta}_{i, t, s e c e-N \mathbb{N}}^{(i)}-\theta_{i, l}^{(i)}\right|=\tilde{o}\left(\frac{1}{T^{1 / 4}}+\frac{1}{\sqrt{N}}\right)
\end{aligned}
$$

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## A near-quadratic improvement over user-NN

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A suitable variant of nearest neighbors improves* upon the user-NN error

$$
\begin{aligned}
\left|\hat{\theta}_{i, t, u s e r-N \mathrm{~N}}^{(a)}-\theta_{i, t}^{(a)}\right| & =\tilde{O}\left(\frac{1}{T^{1 / 4}}+\frac{1}{\sqrt{N}}\right) \\
& \downarrow \\
\left|\hat{\theta}_{i, t, \mathrm{DR}-\mathrm{NN}}^{(a)}-\theta_{i, t}^{(a)}\right| & =\tilde{O}\left(\frac{1}{\sqrt{T}}+\frac{1}{\sqrt{N}}\right)
\end{aligned}
$$

*for Lipschitz non-linearity with Lipschitz gradients \& non-adaptive policies

Proof intuition for user-NN

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Simple case: Estimate $\theta_{i, t}^{(a)} \triangleq f^{(a)}\left(u_{i}^{(a)}, v_{t}^{(a)}\right)=u_{i} v_{t}$

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- $\widehat{\theta}_{i, t, \text { user-NN }}^{(a)}=\frac{\sum_{j \in \text { user-nn }} Y_{j, t}}{\# \text { user-nn }}=\frac{\sum_{j \in \text { user-nn }} \theta_{j, t}^{(a)}+\text { noise }_{j, t}}{\# \text { user-nn }}$


## Proof intuition for user-NN

Simple case: Estimate $\theta_{i, t}^{(a)} \triangleq f^{(a)}\left(u_{i}^{(a)}, v_{t}^{(a)}\right)=u_{i} v_{t}$

- $\hat{\theta}^{(a)}$

$$
\begin{aligned}
&=\frac{\sum_{j \in \text { user-nn }} Y_{j, t}}{\# \text { user-nn }}= \frac{\sum_{j \in \text { user-nn }} \theta_{j, t}^{(a)}+\text { noise }_{j, t}}{\# \text { user-nn }} \\
&= \frac{\sum_{j \in \text { user-nn } u_{j}}^{\# u^{\prime}}}{\hat{u}_{i}} v_{t}+\text { avg.n.noise } \\
& t
\end{aligned}
$$

## Proof intuition for user-NN

Simple case: Estimate $\theta_{i, t}^{(a)} \triangleq f^{(a)}\left(u_{i}^{(a)}, v_{t}^{(a)}\right)=u_{i} v_{t}$

- $\widehat{\theta}_{i, t, \text { user-NN }}^{(a)}=\frac{\sum_{j \in \text { user-nn }} Y_{j, t}}{\# \text { user-nn }}=\frac{\sum_{j \in \text { user-nn }} \theta_{j, t}^{(a)}+\text { noise }_{j, t}}{\# \text { user-nn }}$

$$
\begin{aligned}
&= \frac{\sum_{j \in \text { user-nn } u_{j}}}{\# \text { user-nn }} v_{t}+\text { avg. noise }, \\
& \hat{u}_{i}
\end{aligned}
$$

- $\left|u_{i} v_{t}-\hat{\theta}_{i, t, \text { user-NN }}^{(a)}\right| \leq\left|u_{i} v_{t}-\hat{u}_{i} v_{t}\right|+\mid$ avg. noise $\mid=O\left(\left|u_{i}-\hat{u}_{i}\right|\right)$


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$\hat{\theta}_{i, t, \text { user-NN }}^{(a)}=\frac{\sum_{j \in \text { user-nn }} Y_{j, t}}{\# \text { user-nn }}=\frac{\sum_{j \in \text { user-nn }} \theta_{j, t}^{(a)}+\text { noise }_{j, t}}{\# \text { user-nn }}$

$$
=\frac{\sum_{j \in \text { user-nn }} u_{j}}{\# \text { user-nn }} v_{t}+\text { avg. noise }{ }_{t}
$$

- $\left|u_{i} v_{t}-\hat{\theta}_{i, t, \text { user-NN }}^{(a)}\right| \leq\left|u_{i} v_{t}-\hat{u}_{i} v_{t}\right|+\mid$ avg. noise $\mid \xlongequal{=O\left(\left|u_{i}-\hat{u}_{i}\right|\right)}$


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```
- }\mp@subsup{\hat{0}}{i,t}{(a)
    l,t,user-NN
```



$$
=\frac{\sum_{j \in \text { user-nn }} u_{j}}{\# \text { user-nn }} v_{t}+\text { avg. noise }{ }_{t}
$$

- $\left|u_{i} v_{t}-\hat{\theta}_{i, t, \text { user-NN }}^{(a)}\right| \leq\left|u_{i} v_{t}-\hat{u}_{i} v_{t}\right|+\mid \operatorname{avg} \cdot$ noise $_{t} \mid \stackrel{\leftarrow}{=}\left(\left|u_{i}-\hat{u}_{i}\right|\right)$

$$
\hat{u}_{i}
$$

## Proof intuition for user-NN

Simple case: Estimate $\theta_{i, t}^{(a)} \triangleq f^{(a)}\left(u_{i}^{(a)}, v_{t}^{(a)}\right)=u_{i} v_{t}$

- $\hat{\theta}_{i, t, \text { user-NN }}^{(a)}$


$$
=\frac{\sum_{j \in \text { user }-\mathrm{nn}} u_{j}}{\# \text { user-nn }} v_{t}+\text { avg. noise }{ }_{t}
$$

- $\left|u_{i} v_{t}-\hat{\theta}_{i, t, \text { user-NN }}^{(a)}\right| \leq\left|u_{i} v_{t}-\hat{u}_{i} v_{t}\right|+\mid$ avg. noise $\mid t \stackrel{\leftarrow}{\leftarrow} \stackrel{\left(u_{i}-\hat{u}_{i} \mid\right)}{ }$

$$
\hat{u}_{i}
$$



Martingale concentration, new sandwich argument for $n n$

- $\left|u_{i} v_{t}-\widehat{\theta}_{i, t, \text { time-NN }}^{(a)}\right| \leq\left|u_{i} v_{t}-u_{i} \hat{v}_{t}\right|+\mid$ avg. noise ${ }_{i} \mid=O\left(\left|v_{t}-\hat{v}_{t}\right|\right)$


## Steps towards the improved estimator...

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- Plug-in principle: $\left|u_{i} v_{t}-\hat{u}_{i} \hat{v}_{t}\right| \leq\left|u_{i} v_{t}-\hat{u}_{i} v_{t}\right|+\left|\hat{u}_{i} v_{t}-\hat{u}_{i} \hat{v}_{t}\right|$

$$
=O\left(\left|u_{i}-\hat{u}_{i}\right|+\left|v_{t}-\hat{v}_{t}\right|\right)
$$

## Steps towards the improved estimator...

- Plug-in principle: $\left|u_{i} v_{t}-\hat{u}_{i} \hat{v}_{t}\right| \leq\left|u_{i} v_{t}-\hat{u}_{i} v_{t}\right|+\left|\hat{u}_{i} v_{t}-\hat{u}_{i} \hat{v}_{t}\right|$

$$
=O\left(\left|u_{i}-\hat{u}_{i}\right|+\left|v_{t}-\hat{v}_{t}\right|\right)
$$

- Convert + to $\times: \quad \mid u_{i} v_{t}-? ~ ? ~=O\left(\left|u_{i}-\hat{u}_{i}\right| \times\left|v_{t}-\hat{v}_{t}\right|\right)$


## Steps towards the improved estimator...

- Plug-in principle: $\left|u_{i} v_{t}-\hat{u}_{i} \hat{v}_{t}\right| \leq\left|u_{i} v_{t}-\hat{u}_{i} v_{t}\right|+\left|\hat{u}_{i} v_{t}-\hat{u}_{i} \hat{v}_{t}\right|$

$$
\begin{aligned}
& =O\left(\left|u_{i}-\hat{u}_{i}\right|+\left|v_{t}-\hat{v}_{t}\right|\right) \\
& \approx \max \left\{\left|\hat{u}_{i}-u_{i}\right|,\left|v_{t}-\hat{v}_{t}\right|\right\}
\end{aligned}
$$

- Convert + to $\times: \quad\left|u_{i} v_{t}-? \rightarrow\right|=O\left(\left|u_{i}-\hat{u}_{i}\right| \times\left|v_{t}-\hat{v}_{t}\right|\right)$

$$
\approx \min \left\{\left|\hat{u}_{i}-u_{i}\right|,\left|v_{t}-\hat{v}_{t}\right|\right\}
$$

## What should be our estimator? Let's expand the RHS...

What should be our estimator? Let's expand the RHS...

$$
u_{i} v_{t}-? ?=\left(u_{i}-\hat{u}_{i}\right) \times\left(v_{t}-\hat{v}_{t}\right)
$$

What should be our estimator? Let's expand the RHS...

$$
\begin{aligned}
u_{i} v_{t}-? ? & =\left(u_{i}-\hat{u}_{i}\right) \times\left(v_{t}-\hat{v}_{t}\right) \\
& =u_{i} v_{t}-\hat{u}_{i} v_{t}-u_{i} \hat{v}_{t}+\hat{u}_{i} \hat{v}_{t} \\
\Rightarrow \quad ? & =\hat{u}_{i} v_{t}+u_{i} \hat{v}_{t}-\hat{u}_{i} \hat{v}_{t}
\end{aligned}
$$

What should be our estimator? Let's expand the RHS...

$$
\begin{gathered}
u_{i} b_{t}-? ?=\left(u_{i}-\hat{u}_{i}\right) \times\left(v_{t}-\hat{v}_{t}\right) \\
=u_{i} v_{t}-\hat{u}_{i} v_{t}-u_{i} \hat{v}_{t}+\hat{u}_{i} \hat{v}_{t} \\
\Rightarrow ? ?=\hat{u}_{i} v_{t}+u_{i} \hat{v}_{t}-\hat{u}_{i} \hat{v}_{t} \\
Y_{j, t}+Y_{i, t^{\prime}}-Y_{j, t^{\prime}} \\
\rho_{i, j}^{(a)} \leq \eta, \quad \rho_{t, t^{\prime}}^{(a)} \leq \eta^{\prime}
\end{gathered}
$$

This is our improved nearest neighbors estimator!

$$
\begin{gathered}
u_{i} x_{t}-? ?=\left(u_{i}-\hat{u}_{i}\right) \times\left(v_{t}-\hat{v}_{t}\right) \\
=y_{i} v_{t}-\hat{u}_{i} v_{t}-u_{i} \hat{v}_{t}+\hat{u}_{i} \hat{v}_{t} \\
\Rightarrow \quad ? \quad=\hat{u}_{i} v_{t}+u_{i} \hat{v}_{t}-\hat{u}_{i} \hat{v}_{t} \\
\hat{\theta}_{i, t, \mathrm{DR}-\mathrm{NN}}^{(a)}=\frac{\sum_{j, t^{\prime}}\left(Y_{j, t}+Y_{i, t^{\prime}}-Y_{j, t^{\prime}}\right) \mathbf{1}_{i, t, j, t^{\prime}}}{\sum_{j, t^{\prime}} \mathbf{1}_{i, t, j, t^{\prime}}} \\
\mathbf{1}_{i, t, j, t^{\prime}}=\mathbf{1}\left(\rho_{i, j}^{(a)} \leq \eta, \rho_{t, t^{\prime}}^{(a)} \leq \eta^{\prime}, A_{j, t}=A_{i, t^{\prime}}=A_{j, t^{\prime}}=a\right)
\end{gathered}
$$

This is our improved nearest neighbors estimator!

$$
\begin{aligned}
& u_{i} v_{t}-? ?=\left(u_{i}-\hat{u}_{i}\right) \times\left(v_{t}-\hat{v}_{t}\right) \\
&=u_{i} \nu_{t}-\hat{u}_{i} v_{t}-u_{i} \hat{v}_{t}+\hat{u}_{i} \hat{v}_{t} \\
& \Rightarrow \\
& \text { DR-NN error } \approx \text { user-NN error } \times \text { time-NN error } \\
& \lesssim \min \{\text { user-NN error, time-NN error }\}
\end{aligned}
$$

## This is our improved nearest neighbors estimator!

$$
\begin{aligned}
u_{i} v_{t}-? ? & =\left(u_{i}-\hat{u}_{i}\right) \times\left(v_{t}-\hat{v}_{t}\right) \\
& =u_{i} i_{t}-\hat{u}_{i} v_{t}-u_{i} \hat{v}_{t}+\hat{u}_{i} \hat{v}_{t} \\
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\end{aligned}
$$

DR-NN error $\approx$ user-NN error $\times$ time-NN error § min\{user-NN error, time-NN error\}

Doubly robust to heterogeneity in user factors \& time factors
Double robustness, double machine learning.
[... Cassel+ '77, Robinson '88, Särndal+ '89, Robins+ '94, '95, '08, '09, Newey+ '94, '18, Bickel+ '98, van der Laan+ '03, Lunceford+ '04, Davidian+ '05, Li+ '11, Jiang+ '15, Chernozhukov+ '18, Hirshberg+ '18, Diaz '19, Arkhangelsky+ '21, Dorn+ '21 ...]

## Simulation results

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Uniform latent factors on $[-0.5,0.5]^{4}$, Gaussian noise, pooled $\varepsilon$-greedy policy $(\varepsilon=0.5)$

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Uniform latent factors on $[-0.5,0.5]^{4}$, Gaussian noise, pooled $\varepsilon$-greedy policy ( $\varepsilon=0.5$ )


A baseline
algorithm from
[Chatterjee 2014]

## Simulation results

Uniform latent factors on $[-0.5,0.5]^{4}$, Gaussian noise, pooled $\varepsilon$-greedy policy $(\varepsilon=0.5)$


Decay of avg. error across users ( $\mathrm{N}=\mathrm{T}, 20$ trials)


A baseline
algorithm from
[Chatterjee 2014]

DR-NN error $\ll \boldsymbol{\operatorname { m i n }}\{$ user-NN error, time-NN error \}


## Personalized HeartSteps results 醇 ( $\square$ "

Treatments assigned with Thompson sampling independently for 91 users for 90 days, 5 times a day

## Personalized HeartSteps results 毁＂口＂ネ．．．．

Treatments assigned with Thompson sampling independently for 91 users for 90 days， 5 times a day


## Personalized HeartSteps results

Treatments assigned with Thompson sampling independently for 91 users for 90 days, 5 times a day


## Part 1 summary:

Sample-efficient inference with non-parametric factor models

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Sample-efficient inference with non-parametric factor models
$\sqrt{ }$ Inference in sequential experiments: User-NN with $\tilde{O}\left(T^{-1 / 4}\right)$ error
$\sqrt{ }$ Efficient estimators: Doubly robust-NN with $\tilde{O}\left(T^{-1 / 2}\right)$ error

## DR-NN error $\approx$ user-NN error $\times$ time-NN error § min\{user-NN error, time-NN error\}



- Future: Settings with contexts and covariates

1. Use real data to infer decision's effect

2. Use real data to infer decision's effect

3. Use simulated data to predict decision's effect

Complex multi-scale simulation systems

## Complex multi-scale simulation systems

Cardiology


## Complex multi-scale simulation systems



## Complex multi-scale simulation systems



Computational cardiology: Personalized HeartBeats


Computational cardiology: Personalized HeartBeats


# Computational cardiology: Personalized HeartBeats 



- Dysregulation of calcium signaling in heart cells can cause lethal arrhythmias


## Computational cardiology: Personalized HeartBeats



- Dysregulation of calcium signaling in heart cells can cause lethal arrhythmias
- Task: Simulate multi-scale digital twin models of heart for personalized predictions of dysregulation's effect on a patient's heartbeat


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1. Estimate cell-model parameters with uncertainty quantification with single cell measurements via Bayesian inference and posterior sampling

## Computational cardiology: Personalized HeartBeats



- Dysregulation of calcium signaling in heart cells can cause lethal arrhythmias
- Task: Simulate multi-scale digital twin models of heart for personalized predictions of dysregulation's effect on a patient's heartbeat

1. Estimate cell-model parameters with uncertainty quantification with single cell measurements via Bayesian inference and posterior sampling
2. Propagate cell-model uncertainty to whole-heart model via simulations and Monte Carlo integration

Impact of calcium signaling dysregulation on heartbeat-Two-stage inferential pipeline


Impact of calcium signaling dysregulation on heartbeat-Two-stage inferential pipeline


1. Random sampling via MCMC $X_{1}, \ldots, X_{T} \sim \mathbb{P}^{\star}$ (posterior in $\mathbb{R}^{38}$ )

Impact of calcium signaling dysregulation on heartbeat-Two-stage inferential pipeline


## Standard tasks but computationally challenging...



- $T=10^{6}$ to explore $\mathbb{P}^{\star}$ well


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- $T=10^{6}$ to explore $\mathbb{P}^{\star}$ well
- Time to run MCMC
~ 2 CPU weeks


## Standard tasks but computationally challenging...




- Single $f$ simulation~ 4 CPU weeks
- Time to run MCMC
~ 2 CPU weeks


## Standard tasks but computationally challenging...



Random sampling via MCMC

(posterior in $\mathbb{R}^{38}$ )

- $T=10^{6}$ to explore $\mathbb{P}^{\star}$ well
- Time to run MCMC
~ 2 CPU weeks


Heart model $f$
2. Uncertainty propagation via Monte

Carlo integration (mean, variance,
$\mathbb{P}^{\star} f \triangleq \int f(X) d \mathbb{P}^{\star}(X) \approx \frac{1}{T} \sum_{i=1}^{T} f\left(X_{i}\right)$

- Single $f$ simulation 4 CPU weeks
- Time to compute sample mean
~ 4 Million CPU weeks


## Standard tasks but computationally challenging...

Cell
Cell
model X
model X


Random sampling via MCMC


- $T=10^{6}$ to explore $\mathbb{P}^{\star}$ well
- Time to run MCMC
~ 2 CPU weeks
- How to make MCMC computationally faster?

Heart
model $f$
??

2. Uncertainty propagation via Monte

Carlo integration
$\mathbb{P}^{\star} f \triangleq \int f(X) d \mathbb{P}^{\star}(X) \approx \frac{1}{T} \sum_{i=1}^{T} f\left(X_{i}\right)$

- Single $f$ simulation~ 4 CPU weeks
- Time to compute sample mean ~ 4 Million CPU weeks
- How to make integration computationally feasible?


## Part 2 overview: Computationally-efficient integration for high-dimensional models

> Cell
> model $X$


- $T=10^{6}$ to explore $\mathbb{P}^{\star}$ well
- Time to run MCMC
~ 2 CPU weeks
- How to make MCMC computationally faster?


Random sampling via MCMC


```
(posterior in \mathbb{R}
```


2. Uncertainty propagation via Monte

Carlo integration (mean, variance
$\mathbb{P}^{\star} f \triangleq \int f(X) d \mathbb{P}^{\star}(X) \approx \frac{1}{T} \sum_{i=1}^{T} f\left(X_{i}\right)$

- Single $f$ simulation~ 4 CPU weeks
- Time to compute sample mean ~ 4 Million CPU weeks
- How to make integration computationally feasible?

Efficient integration via distribution compression

## Efficient integration via distribution compression

TIID or MCMC points

$$
\begin{gathered}
X_{1}, \ldots, X_{T} \\
\mathbb{P}_{T} f \triangleq \frac{\Sigma_{i=1}^{T} f\left(X_{i}\right)}{T}
\end{gathered}
$$

## Efficient integration via distribution compression

$T$ IID or MCMC points

$$
\begin{gathered}
X_{1}, \ldots, X_{T} \\
\mathbb{P}_{T} f \triangleq \frac{\Sigma_{i=1}^{T} f\left(X_{i}\right)}{T}
\end{gathered}
$$

$s$ output points (coreset)

$$
\begin{gathered}
X_{1}^{\prime}, \ldots, X_{s}^{\prime} \\
\mathbb{P}_{\text {out }} f \triangleq \frac{\sum_{i=1}^{s} f\left(X_{i}^{\prime}\right)}{S}
\end{gathered}
$$

$s$ (fewer) function evaluations

## Efficient integration via distribution compression

$T$ IID or MCMC points

$$
\begin{gathered}
X_{1}, \ldots, X_{T} \\
\mathbb{P}_{T} f \triangleq \frac{\Sigma_{i=1}^{T} f\left(X_{i}\right)}{T}
\end{gathered}
$$

Compress
$s$ output points (coreset)

$$
\begin{gathered}
X_{1}^{\prime}, \ldots, X_{s}^{\prime} \\
\mathbb{P}_{\text {out }} f \triangleq \frac{\Sigma_{i=1}^{s} f\left(X_{i}^{\prime}\right)}{s}
\end{gathered}
$$

$s$ (fewer) function evaluations

$$
\left|\mathbb{P}^{\star} f-\mathbb{P}_{T} f\right|=\Theta\left(T^{-1 / 2}\right)
$$

## Efficient integration via distribution compression

$T$ IID or MCMC points

$$
\begin{gathered}
X_{1}, \ldots, X_{T} \\
\mathbb{P}_{T} f \triangleq \frac{\Sigma_{i=1}^{T} f\left(X_{i}\right)}{T}
\end{gathered}
$$

$$
\left|\mathbb{P}^{\star} f-\mathbb{P}_{T} f\right|=\Theta\left(T^{-1 / 2}\right)
$$

Standard thinning

uniform sub-sampling
$s$ output points (coreset)

$$
\begin{gathered}
X_{1}^{\prime}, \ldots, X_{s}^{\prime} \\
\mathbb{P}_{\text {out }} f \triangleq \frac{\sum_{i=1}^{s} f\left(X_{i}^{\prime}\right)}{S}
\end{gathered}
$$

$s$ (fewer) function evaluations

$$
\left|\mathbb{P}^{\star} f-\mathbb{P}_{\text {out }} f\right|=\Theta\left(s^{-1 / 2}\right)
$$

$$
\left|\mathbb{P}^{\star} f-\mathbb{P}_{\text {out }} f\right|=\Theta\left(T^{-1 / 4}\right)
$$

$$
\text { when } s=T^{1 / 2}
$$

a million $\rightarrow$ a thousand

TIID or MCMC points
a million $\rightarrow$ a thousand
$\left|\mathbb{P}^{\star} f-\mathbb{P}_{T} f\right|=\Theta\left(T^{-1 / 2}\right) \xrightarrow{\text { Standard thinning }}\left|\mathbb{P}^{\star} f-\mathbb{P}_{\text {out }} f\right|=\Theta\left(T^{-1 / 4}\right)$

## What is the best error we can hope for?

TIID or MCMC points
a million $\rightarrow$ a thousand
$\left|\mathbb{P}^{\star} f-\mathbb{P}_{T} f\right|=\Theta\left(T^{-1 / 2}\right) \xrightarrow{\text { Standard thinning }}\left|\mathbb{P}^{\star} f-\mathbb{P}_{\text {out }} f\right|=\Theta\left(T^{-1 / 4}\right)$

## What is the best error we can hope for?

T IID or MCMC points

$$
\left|\mathbb{P}^{\star} f-\mathbb{P}_{T} f\right|=\Theta\left(T^{-1 / 2}\right) \xrightarrow{\text { Standard thinning }}\left|\mathbb{P}^{\star} f-\mathbb{P}_{\text {out }} f\right|=\Theta\left(T^{-1 / 4}\right)
$$

$\Omega\left(T^{-1 / 2}\right)$ minimax lower bound

- If output = $T^{1 / 2}$ points
- If input = $T$ IID points (any estimator)
[Tolstikhin+ '17, Philips+ '20]


## Prior strategies for efficient integration

$T$ IID or MCMC points

$$
\left|\mathbb{P}^{\star} f-\mathbb{P}_{T} f\right|=\Theta\left(T^{-1 / 2}\right) \xrightarrow{\text { Standard thinning }}\left|\mathbb{P}^{\star} f-\mathbb{P}_{\text {out }} f\right|=\Theta\left(T^{-1 / 4}\right)
$$

## Prior strategies for efficient integration

TIID or MCMC points
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$$
\left|\mathbb{P}^{\star} f-\mathbb{P}_{T} f\right|=\Theta\left(T^{-1 / 2}\right) \xrightarrow{\text { Standard thinning }}\left|\mathbb{P}^{\star} f-\mathbb{P}_{\text {out }} f\right|=\Theta\left(T^{-1 / 4}\right)
$$

| Special $\mathbb{P}^{\star}$ |
| :---: | :--- |
| - Uniform on $[0,1]^{d}$ |
|  |
| special function class |$\quad$| Quasi Monte Carlo, Bayesian quadrature, |
| :--- |
| determinantal point processes, Haar thinning |
| [O'Hagan'91, Hickernell '98, Novak+'10, Liu+ '18, |
| Karvonen+'18, Dwivedi+'19, Belhadji ' 20 ] |

## Prior strategies for efficient integration

TIID or MCMC points
a million $\rightarrow$ a thousand
$T^{1 / 2}$ output points

$$
\left|\mathbb{P}^{\star} f-\mathbb{P}_{T} f\right|=\Theta\left(T^{-1 / 2}\right) \xrightarrow{\text { Standard thinning }}\left|\mathbb{P}^{\star} f-\mathbb{P}_{\text {out }} f\right|=\Theta\left(T^{-1 / 4}\right)
$$

Special $\mathbb{P}^{\star}$

- Uniform on $[0,1]^{d}$
- Bounded support \&

special function class $\quad$| $o\left(T^{-1 / 4}\right)$ error guarantee: |
| :--- |
| Quasi Monte Carlo, Bayesian quadrature, |
| determinantal point processes, Haar thinning |
| [O'Hagan '91, Hickernell '98, Novak+'10, Liu+ '18, |
| Karvonen+'18, Dwivedi'+'19, Belhadji ' '20] |


$T$ IID or MCMC points
a million $\rightarrow$ a thousand
$\left|\mathbb{P}^{\star} f-\mathbb{P}_{T} f\right|=\Theta\left(T^{-1 / 2}\right) \xrightarrow{\text { Standard thinning }}\left|\mathbb{P}^{\star} f-\mathbb{P}_{\text {out }} f\right|=\Theta\left(T^{-1 / 4}\right)$

## A new practical \& provably near-optimal procedure

$T$ IID or MCMC points

$$
\left|\mathbb{P}^{\star} f-\mathbb{P}_{T} f\right|=\Theta\left(T^{-1 / 2}\right) \xrightarrow{\text { Standard thinning }}\left|\mathbb{P}^{\star} f-\mathbb{P}_{\text {out }} f\right|=\Theta\left(T^{-1 / 4}\right)
$$

## Visual comparison on $\mathbb{P}^{\star}=8$ mixture of Gaussian

64 iid input points

8 output points



Visual comparison on $\mathbb{P}^{\star}=8$ mixture of Gaussian
64 iid input points

8 output points



Quantitative measure: Worst-case error over a rich class

## Quantitative measure: Worst-case error over a rich class

Namely, over the unit ball of a reproducing kernel Hilbert space (RKHS)

$$
\sup _{\|f\|_{\mathbf{k}} \leq 1}\left|\mathbb{P}^{\star} f-\mathbb{P}_{\text {out }} f\right|
$$

## Quantitative measure: Worst-case error over a rich class

Namely, over the unit ball of a reproducing kernel Hilbert space (RKHS)

$$
\sup _{\|f\|_{\mathbf{k}} \leq 1}\left|\mathbb{P}^{\star} f-\mathbb{P}_{\text {out }} f\right|
$$

- Parameterized by a reproducing kernel $\mathbf{k}$ any symmetric $(\mathbf{k}(x, y)=\mathbf{k}(y, x))$ and positive semidefinite function



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$$

- Parameterized by a reproducing kernel $\mathbf{k}$ any symmetric $(\mathbf{k}(x, y)=\mathbf{k}(y, x))$ and positive semidefinite function
- Metrizes convergence in distribution for popular infinite-dimensional $\mathbf{k}$


Main result: A high probability bound for generic $\mathbb{P}^{\star}$ and $\mathbf{k}$

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Informal theorem: [Dwivedi and Mackey'21, '22 and Dwivedi-Shetty-Mackey '22]
Kernel thinning uses $O\left(T \log ^{3} T\right)$ kernel evaluations to output $T^{1 / 2}$ points, that with high probability satisfy

## Main result: $A$ high probability bound for generic $\mathbb{P}^{\star}$ and $\mathbf{k}$

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Kernel thinning uses $O\left(T \log ^{3} T\right)$ kernel evaluations to output $T^{1 / 2}$ points, that with high probability satisfy

- $\left|\mathbb{P}^{\star} f-\mathbb{P}_{\text {out }} f\right| \lesssim \sqrt{\frac{\log T}{T}} \cdot\|f\|_{\mathbf{k}} \sqrt{\|\mathbf{k}\|_{\infty}}$ for a fixed $f$ in the RKHS of $\mathbf{k}$ (any kernel) when $\left|\mathbb{P}^{\star} f-\mathbb{P}_{T} f\right| \lesssim T^{-1 / 2}$
- A near-quadratic gain over $T^{-1 / 4}$ standard thinning error


## Main result: A high probability bound for generic $\mathbb{P}^{\star}$ and $\mathbf{k}$

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- $\sup _{\|f\|_{\mathrm{k}} \leq 1}\left|\mathbb{P}^{\star} f-\mathbb{P}_{\text {out }} f\right| \lesssim \sqrt{\frac{\log ^{d / 2+1} T}{T}}$ Sub-gaussian $\mathbb{P}^{\star}$ and $\mathbf{k}$ on $\mathbb{R}^{d}$ (Gaussian)

$$
\lesssim \sqrt{\frac{\log ^{d+1} T}{T}} \text { Sub-exponential } \mathbb{P}^{\star} \text { and } \mathbf{k} \text { on } \mathbb{R}^{d} \text { (Matérn) }
$$

- A near-quadratic gain over $T^{-1 / 4}$ standard thinning error
- Matches minimax lower bounds $T^{-1 / 2}$ up to log factors

Kernel thinning

$$
\begin{gathered}
\text { points } \\
X_{1}, X_{2}, \ldots, X_{T}
\end{gathered} \rightarrow \text { Kernel } \rightarrow \begin{gathered}
\text { functions in RKHS } \\
v_{1}, v_{2}, \ldots, v_{T}
\end{gathered}
$$

## Kernel thinning $\equiv$ Recursive halving via kernel evaluations

$$
\begin{gathered}
\text { points } \\
X_{1}, X_{2}, \ldots, X_{T}
\end{gathered} \rightarrow \text { Kernel } \rightarrow \begin{gathered}
\text { functions in RKHS } \\
v_{1}, v_{2}, \ldots, v_{T}
\end{gathered}
$$

$\underset{T \text { points }}{\text { Input }} \rightarrow \underset{\text { Kernel }}{\text { Kalving }} \rightarrow \underset{\text { points }}{T / 2} \rightarrow \underset{\substack{\text { Kernel halving } \\ \text { rounds }}}{O(\log T)} \rightarrow \underset{\sqrt{T} \text { points }}{\text { Output }}$ + some refinement

## Kernel halving

$$
\begin{gathered}
\text { points } \\
X_{1}, X_{2}, \ldots, X_{T} \rightarrow \text { Kernel } \rightarrow \begin{array}{c}
\text { functions in RKHS } \\
v_{1}, v_{2}, \ldots, v_{T}
\end{array}
\end{gathered}
$$

$v_{1}, v_{2}, \ldots, v_{T} \rightarrow \begin{gathered}\text { Kernel } \\ \text { halving }\end{gathered} \rightarrow v_{1}^{\prime}, v_{2}^{\prime}, \ldots, v_{T / 2}^{\prime}$

$$
\left|\frac{\Sigma_{i=1}^{T} v_{i}}{T}-\frac{\Sigma_{i=1}^{T / 2} v_{i}^{\prime}}{T / 2}\right|=\text { small }
$$

## Kernel halving $\equiv$ Discrepancy minimization problem



## Kernel halving $\equiv$ Discrepancy minimization problem

$$
\begin{aligned}
& \begin{array}{c}
\text { points } \\
X_{1}, X_{2}, \ldots, X_{T}
\end{array} \rightarrow \text { Kernel } \rightarrow \begin{array}{c}
\text { functions in RKHS } \\
v_{1}, v_{2}, \ldots, v_{T}
\end{array} \\
& \begin{array}{c}
v_{1}, v_{2}, \ldots, v_{T} \rightarrow \begin{array}{c}
\text { Kernel } \\
\text { halving }
\end{array} \rightarrow v_{1}^{\prime}, v_{2}^{\prime}, \ldots, v_{T / 2}^{\prime}
\end{array} \begin{array}{c}
\text { Assign } \varepsilon_{i} \in\{-1,1\} \text { to } v_{i} \\
\text { such that }\left|\sum_{i=1}^{T} \varepsilon_{i} v_{i}\right| \text { is small } \\
\text { \& output points with } \varepsilon_{i}=-1
\end{array}
\end{aligned}
$$

## Kernel halving $\equiv$ Discrepancy minimization problem

$$
\begin{aligned}
& \begin{array}{c}
\text { points } \\
X_{1}, X_{2}, \ldots, X_{T}
\end{array} \rightarrow \text { Kernel } \rightarrow \begin{array}{c}
\text { functions in RKHS } \\
v_{1}, v_{2}, \ldots, v_{T}
\end{array}
\end{aligned}
$$

## Kernel halving $\equiv$ Discrepancy minimization problem

$$
\begin{aligned}
& \begin{array}{c}
\text { points } \\
X_{1}, X_{2}, \ldots, X_{T}
\end{array} \rightarrow \begin{array}{c}
\text { functions in RKHS } \\
v_{1}, v_{2}, \ldots, v_{T}
\end{array}
\end{aligned}
$$

## Kernel halving $\equiv$ Discrepancy minimization problem



KT intuition: IID vs correlated signs
$\left|\Sigma_{i=1}^{T} \varepsilon_{i} v_{i}\right|$ is small

## KT intuition: IID vs correlated signs

$$
\left|\Sigma_{i=1}^{T} \varepsilon_{i} v_{i}\right| \text { is small }
$$<br>$\varepsilon_{i}= \pm 1$ with equal probability

## KT intuition: IID vs correlated signs

$$
\begin{aligned}
& \qquad \frac{\left|\Sigma_{i=1}^{T} \varepsilon_{i} v_{i}\right| \text { is small }}{\varepsilon_{i}}=\begin{aligned}
& = \pm 1 \text { with equal probability } \\
\sigma_{T}^{2} & =\sigma_{T-1}^{2}+v_{T}^{2} \\
\left|\Sigma_{i=1}^{T} \varepsilon_{i} v_{i}\right| & =O\left(\sigma_{T}\right)=O\left(T^{1 / 2}\right)
\end{aligned}
\end{aligned}
$$

Standard thinning

## KT intuition: IID vs correlated signs

$$
\begin{gathered}
\qquad\left|\Sigma_{i=1}^{T} \varepsilon_{i} v_{i}\right| \text { is small } \\
\varepsilon_{i}= \pm 1 \text { with equal probability } \\
\sigma_{T}^{2}=\sigma_{T-1}^{2}+v_{T}^{2} \\
\left|\Sigma_{i=1}^{T} \varepsilon_{i} v_{i}\right|=O\left(\sigma_{T}\right)=O\left(T^{1 / 2}\right) \\
\text { Standard thinning }
\end{gathered}
$$

## KT intuition: IID vs correlated signs

$$
\begin{array}{c|}
\left|\Sigma_{i=1}^{T} \varepsilon_{i} v_{i}\right| \text { is small } \\
\varepsilon_{i}= \pm 1 \text { with equal probability } \\
\sigma_{T}^{2}=\sigma_{T-1}^{2}+v_{T}^{2} \\
\left|\Sigma_{i=1}^{T} \varepsilon_{i} v_{i}\right|=O\left(\sigma_{T}\right)=O\left(T^{1 / 2}\right) \\
\varepsilon_{i} \text { negatively correlated with } \sum_{j=1}^{i-1} \varepsilon_{j} v_{j} \\
\text { Standard thinning }
\end{array}
$$

## KT intuition: IID vs correlated signs

$$
\begin{array}{c|}
\left|\Sigma_{i=1}^{T} \varepsilon_{i} v_{i}\right| \text { is small } \\
\varepsilon_{i}= \pm 1 \text { with equal probability } \\
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\text { Standard thinning }
\end{array}
$$

## KT intuition: IID vs correlated signs

$$
\left.\begin{array}{c|}
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\varepsilon_{i}= \pm 1 \text { with equal probability } \\
\sigma_{T}^{2}=\sigma_{T-1}^{2}+v_{T}^{2} \\
\left|\Sigma_{i=1}^{T} \varepsilon_{i} v_{i}\right|=O\left(\sigma_{T}\right)=O\left(T^{1 / 2}\right) \\
\\
\text { Standard thinning }
\end{array} \right\rvert\, \begin{array}{cc}
\sigma_{T}^{2} \leq \beta \sigma_{T-1}^{2}+v_{T}^{2} \text { for } \beta<1 \\
\left|\Sigma_{i=1}^{T} \varepsilon_{i} v_{i}\right|=O\left(\sigma_{T}\right)=O(\sqrt{\log T}) \\
\text { Kernel thinning }
\end{array}
$$

## KT intuition: IID vs correlated signs

$$
\begin{aligned}
& \left|\Sigma_{i=1}^{T} \varepsilon_{i} v_{i}\right| \text { is small } \\
& \varepsilon_{i}= \pm 1 \text { with equal probability } \\
& \sigma_{T}^{2}=\sigma_{T-1}^{2}+v_{T}^{2} \\
& \left|\Sigma_{i=1}^{T} \varepsilon_{i} v_{i}\right|=O\left(\sigma_{T}\right)=O\left(T^{1 / 2}\right) \\
& \text { Standard thinning } \\
& \varepsilon_{i} \text { negatively correlated with } \sum_{j=1}^{i-1} \varepsilon_{j} v_{j} \\
& \sigma_{T}^{2} \leq \beta \sigma_{T-1}^{2}+v_{T}^{2} \text { for } \beta<1 \\
& \left|\Sigma_{i=1}^{T} \varepsilon_{i} v_{i}\right|=O\left(\sigma_{T}\right)=O(\sqrt{\log T}) \\
& \text { Kernel thinning } \\
& \text { Discrepancy minimization } \\
& \text { [... Spencer '77, Banaszczyk '98, '12, Eldan+ '18, }
\end{aligned}
$$

## Is $K T$ better practically? Gaussian $\mathbb{P}^{\star}$ in $\mathbb{R}^{d}$

iid input, Gaussian kernel

Output size $\sqrt{T}$

## Is $K T$ better practically? Gaussian $\mathbb{P}^{\star}$ in $\mathbb{R}^{d}$

iid input, Gaussian kernel


## Is KT better practically? Gaussian $\mathbb{P}^{\star}$ in $\mathbb{R}^{d}$

iid input, Gaussian kernel





## Is $K T$ better practically? Gaussian $\mathbb{P}^{\star}$ in $\mathbb{R}^{d}$

iid input, Gaussian kernel




Significant gains in $d=100$ with just 8 output points

KT on MCMC points for $\mathbb{P}^{\star}$ in experiments $(d=38)$

$$
{ }^{\dagger} \text { Input }=2 \mathrm{MCMC} \text { runs on } 2 \text { posteriors } \mathbb{P}^{\star}, \text { Gaussian kernel }
$$

KT on MCMC points for $\mathbb{P}^{\star}$ in experiments $(d=38)$

$$
{ }^{\dagger} \text { Input }=2 \mathrm{MCMC} \text { runs on } 2 \text { posteriors } \mathbb{P}^{\star}, \text { Gaussian kernel }
$$

## KT on MCMC points for $\mathbb{P}^{\star}$ in experiments $(d=38)$

$\dagger$ Input $=2 \mathrm{MCMC}$ runs on 2 posteriors $\mathbb{P}^{\star}$, Gaussian kernel

Cardiology 1


Cardiology 2


Cardiology 3


Cardiology 4


Standard thinning does well but KT provides further improvement \& offers 50\% computational savings (each point $\sim 4$ CPU weeks)

Kernel thinning: Near-optimal compression in near-linear time

# Kernel thinning: Near-optimal compression in near-linear time 

 R python pip install goodpointsThin 100k points in 100 dimensions in 10mins



## From HeartSteps



## From HeartSteps



Sequential
experiments



Uncertainty
propagation
propagation
to HeartBeats


Uncertainty
propagation
propagation
to HeartBeats

Personalized simulations by thinning neighborhoods

Quadratic gains via discrepancy minimization


Uncertainty
propagation
to HeartBeats

Personalized simulations by thinning neighborhoods

Quadratic gains via discrepancy minimization


Personalized inference by averaging neighborhoods

Quadratic gains via double robustness

experiments


Uncertainty
propagation

## to HeartBeats

Personalized simulations by thinning neighborhoods

Quadratic gains via discrepancy minimization

$\uparrow$

Sequential
experiments


Model
88


# Deep dive into personalization by a 

 reinforcement learning algorithm

Dwivedi*-Zhang*-Chhabria-Klasnja-
Sequential
experiments


Stable discovery of interpretable subgroups in
randomized studies via calibration


Dwivedi*-Tan*-Park-Wei-Horgan-Madigan-Yu '20


Stable discovery of interpretable subgroups in

On counterfactual inference with unobserved confounding via exponential family


Shah-Dwivedi-Shah-Wornell '22
randomized studies via calibration


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Deep dive into personalization by a reinforcement learning algorithm


Dwivedi*-Zhang*-Chhabria-KlasnjaMurphy '23

Fast and powerful kernel testing via distribution compression


Shetty-Dwivedi-Mackey '22,
Domingo Enrich-Dwivedi-Mackey '23

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Statistical-computational tradeoffs for optimization algorithms

Mixing time guarantees for MCMC algorithms in high dimensions


Dwivedi*-Ho*-Khamaru*-Wainwright-Jordan-Yu '19, '20, '21, '22+

Stable discovery of interpretable subgroups in

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Deep dive into personalization by a reinforcement learning algorithm


Dwivedi*-Zhang*-Chhabria-KlasnjaMurphy '23

Fast and powerful kernel testing via distribution compression


Shetty-Dwivedi-Mackey '22,
Domingo Enrich-Dwivedi-Mackey '22


Mixing time guarantees for MCMC algorithms in high dimensions


Dwivedi*-Ho*-Khamaru*-Wainwright-Jordan-Yu '19, '20, '21, '22+



Thank you!

Appendix

Propensity-adjusted user nearest neighbors estimator for $\theta_{i, t}^{(a)}$

Distance between two users $i$ and $j$ under treatment $a=$ squared distance between their outcomes averaged over all times when both treated with $a$

$$
\rho_{i, j}^{(a)}=\frac{\sum_{t^{\prime}=1}^{T}\left(Y_{i, t^{\prime}}-Y_{j, t^{\prime}}\right)^{2} \cdot \mathbf{1}\left(A_{i, t}=A_{j, t^{\prime}}=a\right)}{\sum_{t^{\prime}=1}^{T} \mathbf{1}\left(A_{i, t^{\prime}}=A_{j, t^{\prime}}=a\right)}
$$

Estimate $=$ Averaged outcome across user neighbors treated with $a$ at time $t$

Propensity-adjusted user nearest neighbors estimator for $\theta_{i, t}^{(a)}$

Distance between two users $i$ and $j$ under treatment $a=$ squared distance between their outcomes averaged over all times when both treated with $a$

$$
\rho_{i, j}^{(a)}=\frac{\sum_{t^{\prime}=1}^{T}\left(Y_{i, t^{\prime}}-Y_{j, t^{\prime}}\right)^{2} \cdot \mathbf{1}\left(A_{i, t^{\prime}}=A_{j, t^{\prime}}=a\right)}{\sum_{t^{\prime}=1}^{T} \mathbf{1}\left(A_{i, t^{\prime}}=A_{j, t^{\prime}}=a\right)} \rightarrow \frac{\sum_{t^{\prime}=1}^{T}\left(Y_{i, t^{\prime}}-Y_{j, t^{\prime}}\right)^{2} \cdot \frac{\mathbf{1}\left(A_{i, t^{\prime}}=A_{j, t^{\prime}}=a\right)}{\mathbb{P}\left(1\left(A_{i, t^{\prime}}=A_{j, t^{\prime}}=a\right) \mid \mathscr{F}_{\left.t^{\prime}\right)}\right)}}{\sum_{t^{\prime}=1}^{T} \frac{\mathbf{1}\left(A_{i, t^{\prime}}=A_{j, t^{\prime}}=a\right)}{\mathbb{P}\left(1\left(A_{i, t^{\prime}}=A_{j, t^{\prime}}=a\right) \mid \mathscr{F}_{t^{\prime}}\right)}}
$$

Estimate $=$ Averaged outcome across user neighbors treated with $a$ at time $t$

## Propensity-adjusted user nearest neighbors estimator for $\theta_{i, t}^{(a)}$

Distance between two users $i$ and $j$ under treatment $a=$ squared distance between their outcomes averaged over all times when both treated with $a$

$$
\rho_{i, j}^{(a)}=\frac{\sum_{t^{\prime}=1}^{T}\left(Y_{i, t^{\prime}} Y_{j, t^{\prime}}\right)^{2} \cdot \mathbf{1}\left(A_{i, t^{\prime}}=A_{j, t^{\prime}}=a\right)}{\sum_{t^{\prime}=1}^{T} \mathbf{1}\left(A_{i, t^{\prime}}=A_{j, t^{\prime}}=a\right)} \rightarrow \frac{\sum_{t^{\prime}=1}^{T}\left(Y_{i, t^{\prime}}-Y_{j, t^{\prime}}\right)^{2} \cdot \frac{\mathbf{1}\left(A_{i, t^{\prime}}=A_{j, t^{\prime}}=a\right)}{\mathbb{P}\left(1\left(A_{i, t^{\prime}}=A_{j, t^{\prime}}=a\right) \mid \mathscr{F}_{\left.t^{\prime}\right)}\right)}}{\sum_{t^{\prime}=1}^{T} \frac{\mathbf{1}\left(A_{i, t^{\prime}}=A_{j, t^{\prime}}=a\right)}{\mathbb{P}\left(1\left(A_{i, t^{\prime}}=A_{j, t^{\prime}}=a\right) \mid \mathscr{F}_{\left.t^{\prime}\right)}\right)}}
$$

Estimate $=$ Averaged outcome across user neighbors treated with $a$ at time $t$


Allows non-iid time factors albeit with worse variance

## IID signs

## VS <br> Correlated signs

$$
\left|\Sigma_{i=1}^{T} \varepsilon_{i} \nu_{i}\right| \text { is small }
$$

$$
\begin{aligned}
\varepsilon_{i}= & \left\{\begin{array}{l}
+1 \text { w.p. } 0.5 \\
-1 \\
\text { w.p. } 0.5
\end{array}\right. \\
\bullet \sigma_{T}^{2} & \triangleq \operatorname{Var}\left(\Sigma_{i=1}^{T-1} \varepsilon_{i} v_{i}+\varepsilon_{T} v_{T}\right) \\
& =\operatorname{Var}\left(\Sigma_{i=1}^{T-1} \varepsilon_{i} v_{i}\right)+\operatorname{Var}\left(\varepsilon_{T} v_{T}\right)+2 \mathbb{E}\left[\varepsilon_{T} \psi_{T-1} v_{T}\right] \\
& =\sigma_{T-1}^{2}+v_{T}^{2}=\Sigma_{i=1}^{T} v_{T}^{2}=O(T)
\end{aligned}
$$

- $\left|\Sigma_{i=1}^{T} \varepsilon_{i} v_{i}\right|=O\left(\sigma_{T}\right)=O\left(T^{1 / 2}\right)$

$$
\begin{aligned}
& \varepsilon_{i}=\left\{\begin{array} { l } 
{ + 1 \text { w.p. } 0 . 5 ( 1 - \psi _ { i - 1 } v _ { i } / a ) } \\
{ - 1 \text { w.p. } 0 . 5 ( 1 + \psi _ { i - 1 } v _ { i } / a ) }
\end{array} \quad \left[\begin{array}{l}
\mathbb{E}\left[\varepsilon_{i} \psi_{i-1} v_{i}\right]<0
\end{array}\right.\right. \\
& \bullet \sigma_{T}^{2} \\
&=\operatorname{Var}\left(\Sigma_{i=1}^{T-1} \varepsilon_{i} v_{i}\right)+\operatorname{Var}\left(\varepsilon_{T} v_{T}\right)-2 \mathbb{E}\left[\psi_{T-1}^{2} v_{T}^{2} / a\right] \\
& \leq \beta \sigma_{T-1}^{2}+v_{T}^{2} \text { for some } \beta<1^{\dagger} \\
& \leq a /(1-\beta) \leq \log T
\end{aligned}
$$

- $\left|\Sigma_{i=1}^{T} \varepsilon_{i} v_{i}\right|=O\left(\sigma_{T}\right)=O(\sqrt{\log T})$

Kernel thinning

## Non-linear double/squared robustness

- $f(u, 0)=f(0,0)+f_{u}^{\prime}(0,0) u+\quad+f_{u u}^{\prime \prime}(\tilde{u}, 0) u^{2}$
- $f(0, v)=f(0,0)+\quad+f_{v}^{\prime}(0,0) v+f_{v v}^{\prime \prime}(0, \hat{v}) v^{2}$
- $f(u, v)=f(0,0)+f_{u}^{\prime}(0,0) u+f_{v}^{\prime}(0,0) v+[u, v] \nabla^{2} f(\tilde{u}, \tilde{v})\left[\begin{array}{l}u \\ v\end{array}\right]$
- $f(u, 0)+f(0, v)-f(u, v)=f(0,0)+O\left((u+v)^{2}\right) \Longrightarrow$ Error $=\max \left\{u^{2}, v^{2}\right\}$


## Additional results for Personalized Heartsteps




## Additional results for Personalized Heartsteps




## Additional results for Personalized Heartsteps



Histogram across 20 users at 50 times for $a=1$ (test data)


