From HeartSteps to HeartBeats: Personalized Decision-making







Stanford University, OIT Seminar, Jan 25

Raaz Dwivedi





Driven by extensive data collection, decreasing cost of computation, synergy between disciplines



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Personalized Decision-making



















1. Use **real data** to infer decision's effect







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How to assign personalized digital treatments to help you?



How to assign personalized digital treatments to help you?







How to assign personalized digital treatments to help you?









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Mobile health study: [Liao+ '20] **Personalized HeartSteps**

- **Goal**: Promote physical activity via mobile app
- Population: 91 hypertension patients, 90 days



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PTSD Coach



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- Treatment: Mobile notifications 5 times/day assigned by a bandit algorithm





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Mobile health study: [Liao+ '20] Personalized HeartSteps

- **Goal**: Promote physical activity via mobile app
- Population: 91 hypertension patients, 90 days
- Treatment: Mobile notifications 5 times/day assigned by a bandit algorithm
- **Outcome**: 30-min step count after decision time



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B Did the app increase physical activity for a given <u>user</u>?

Was sending the notification effective?

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- B Did the app increase physical activity for a given <u>user</u>?
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 - Was the bandit algorithm effective?

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How to assign personalized digital treatments to help you?



- **O**ID Did the app increase physical activity for a <u>given</u> <u>user</u>?
 - Was sending the notification effective?
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- **Challenges**: Lack of mechanistic models, adaptively collected data, expensive data collection





How to assign personalized digital treatments to help you?



PTSD Coach



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Part 1 overview: Sample-efficient personalized inference in sequential experiments

② Did the app increase physical activity for a given How to assign personalized digital treatments to help you? user? This talk



PTSD Coach





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 $A_{i,t}$: treatment $\in \{0,1\}$ (send a notification or not) assigned using policy_{*i*,t}





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e.g., ε -greedy, Thompson sampling, softmax, multiplicative weights, pooled variants,...

Sequentially adaptive policy that **can pool** observed data <u>across users</u> to speed up learning





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[Neyman-Rubin framework]

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outcome observed: $Y_{i,t} = \theta_{i,t}^{(A_{i,t})} + \text{noise}_{i,t}$ [Neyman-Rubin framework + SUTVA]

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Sequentially adaptive policy that **can pool** observed data across users to speed up learning

Estimate counterfactual means $\{\theta_{it}^{(a)}\}$ for $a \in \{0,1\}$ all N users & T times

- Enable generic after-study analyses and assist next study design
- E.g., how effective was the notification for user *i* at time $t (\theta_{i,t}^{(1)} - \theta_{i,t}^{(0)})$?







Challenges:

More unknowns than (noisy) observations



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Hope:

 \star N iid users



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- \star N iid users
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- ★ If users are not all too different & multiple observations can help find similarities



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Estimate counterfactual means $\{\theta_{it}^{(a)}\}$ for $a \in \{0,1\}$, all N users & T times

Prior work:

Average treatment effect



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Prior work:

- Average treatment effect
 - IID users & deterministic rules/policies
 - IID users at each time with stochastic policies
 - IID user trajectories (per user policy, no pooling)
- Observational studies (once treated forever treated; synthetic control, causal panel data)

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 $Y_{i,t} = \theta_{i,t}^{(A_{i,t})} + \text{noise}_{i,t}$



 $\theta_{i,t}^{(a)} \triangleq f^{(a)}(u_i^{(a)}, v_t^{(a)})$

user factor

time factor (e.g., personal (e.g., societal, weather traits) changes)

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No parametric assumptions on

- **unknown** non-linearity
- distributions of unobserved latent factors and noise

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T time factors

N user factors





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T time factors



User nearest neighbors estimator for $\theta_{i,t}^{(a)}$

 $Y_{i,t} = \theta_{i,t}^{(A_{i,t})} + \text{noise}_{i,t}$



User nearest neighbors estimator for $\theta_{i,t}^{(a)}$ $Y_{i,t} = \theta_{i,t}^{(A_{i,t})} + \text{noise}_{i,t}$

1. Compute distance between two users *i* and *j* under treatment *a*



User nearest neighbors estimator for $\theta_{i,t}^{(a)}$ $Y_{i,t} = \theta_{i,t}^{(A_{i,t})} + \text{noise}_{i,t}$

1. Compute distance between two users *i* and *j* under treatment *a*

$$\rho_{i,j}^{(a)} = \frac{\sum_{t'=1}^{T} (Y_{i,t'} - Y_{j,t'})^2 \cdot \mathbf{1}(A_{i,t'} = A_{j,t'} = a)}{\sum_{t'=1}^{T} \mathbf{1}(A_{i,t'} = A_{j,t'} = a)}$$



User nearest neighbors estimator for $\theta_{it}^{(a)}$ $Y_{i,t} = \theta_{i,t}^{(A_{i,t})} + \text{noise}_{i,t}$

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Squared distance between outcomes averaged over **<u>all times</u> when** *i* **and** *j* are both treated with a





User nearest neighbors estimator for $\theta_{i,t}^{(a)}$ $Y_{i,t} = \theta$

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2. Average outcome across user neighbors treated with a at time t

1

$$P_{i,t}^{(A_{i,t})} + \text{noise}_{i,t}$$

Squared distance between outcomes averaged over **all times** when *i* and *j* are both treated with a

$$(\rho_{i,j}^{(a)} \leq \eta, A_{j,t} = a)$$





User nearest neighbors estimator for $\theta_{it}^{(a)}$ $Y_{i,t} = \theta$

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2. Average outcome across user neighbors treated with a at time t

$$\widehat{\theta}_{i,t,\text{user-NN}}^{(a)} = \frac{\sum_{j=1}^{N} Y_{j,t} \cdot \mathbf{1}(\rho_{i,j}^{(a)} \leq \eta, A_{j,t} = a)}{\sum_{j=1}^{N} \mathbf{1}(\rho_{i,j}^{(a)} \leq \eta, A_{j,t} = a)}$$

$$P_{i,t}^{(A_{i,t})} + \text{noise}_{i,t}$$

Squared distance between outcomes averaged over **<u>all times</u>** when *i* and *j* are both treated with a





Main result: A non-asymptotic guarantee for each (i, t, a)
Informal theorem: [Dwivedi-Tian-Tomkins-Klasnja-Murphy-Shah '22a] For suitably chosen η & under regularity conditions

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(†Our general results allow p to decay as $\gtrsim T^{-1/2}$)

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for each user *i* at each time *t*, with high probability

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- Lipschitz non-linearity, iid latent factors, sub-Gaussian noise
- generic sequentially adaptive policies that assign treatments independently to users conditioned on observed history & choose *a* with probability $\geq p^{\dagger}$
- for each user *i* at each time *t*, with high probability $|\hat{\theta}_{i,t,\text{user-NN}}^{(a)} - \theta_{i,t}^{(a)}| \lesssim \frac{1}{T^{1/4}} + \frac{1}{(N/M)^{1/2}}$

(†Our general results allow p to decay as $\gtrsim T^{-1/2}$)



User factor distribution (Uniform on finite set of size M)

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User factor distribution (Uniform on finite set of size M) (Uniform over $[-1,1]^d$)



• Asymptotic confidence intervals as $N, T \to \infty$: $\hat{\theta}_{i,t,\text{user-NN}}^{(a)} \pm \frac{1.96\hat{\sigma}}{\sqrt{\#\text{neighbors}}_{i,t,a}}$

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Confidence intervals for treatment effect $\theta_{i,t}^{(1)} - \theta_{i,t}^{(0)}$

• Asymptotic **confidence intervals** as $\hat{\theta}_{i,t,\text{user-NN}}^{(a)} \pm \frac{1.96\hat{\sigma}}{\sqrt{\#\text{neighbors}_{i,t,a}}}$

Confidence intervals for treatment effect $\theta_{i,t}^{(1)} - \theta_{i,t}^{(0)}$

• Asymptotic confidence intervals as $N, T \rightarrow \infty$: for user-time-level counterfactuals

 \checkmark More unknowns than observations

✓ Non-parametric model

✓ Heterogeneity across users & time

✓ Generic sequential policies



• Asymptotic confidence intervals as $N, T \rightarrow \infty$: $\hat{\theta}_{i,t,\text{user-NN}}^{(a)} \pm \frac{1.96\hat{\sigma}}{\sqrt{\#\text{neighbors}}}$ • $|\hat{\theta}_{i,t,\text{user-NN}}^{(a)} - \theta_{i,t}^{(a)}| = \tilde{O}\left(\frac{1}{T^{1/4}} + \frac{1}{\sqrt{N}}\right)$

Challenges tackled: First guarantee for user-time-level counterfactuals

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 $\hat{\theta}_{i,t,\text{user-NN}}^{(a)} \pm \frac{1.96\hat{\sigma}}{\sqrt{\#\text{neighbors}}}$ • $\left| \hat{\theta}_{i,t,\text{user-NN}}^{(a)} - \theta_{i,t}^{(a)} \right| = \tilde{O}\left(\frac{1}{T^{1/4}} + \frac{1}{\sqrt{N}} \right)$ $|?? - \theta_{i,t}^{(a)}| = \tilde{O}\left(\frac{1}{\sqrt{T}} + \frac{1}{\sqrt{N}}\right)$

Challenges tackled: First guarantee • Asymptotic confidence intervals as $N, T \rightarrow \infty$: for user-time-level counterfactuals

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Yes, we can! A near-quadratic improvement over user-NN

Yes, we can! A near-quadratic improvement over user-NN Informal theorem: [Dwivedi-Tian-Tomkins-Klasnja-Murphy-Shah '22b] A suitable variant of nearest neighbors improves* upon the user-NN error

$$|\hat{\theta}_{i,t,\text{user-NN}}^{(a)} - \theta_{i,t}^{(a)}| =$$

$$\widehat{\theta}_{i,t,\text{DR-NN}}^{(a)} - \theta_{i,t}^{(a)} | =$$



Yes, we can! A near-quadratic improvement over user-NN **Informal theorem:** [**Dwivedi**-Tian-Tomkins-Klasnja-Murphy-Shah '22b] A suitable variant of nearest neighbors improves* upon the user-NN error

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*for Lipschitz non-linearity with Lipschitz gradients & non-adaptive policies

Simple case: Estimate $\theta_{i,t}^{(a)} \triangleq f^{(a)}(u_i^{(a)}, v_t^{(a)}) = u_i v_t$

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 $_{j \in \text{user-nn}} \theta_{j,t}^{(a)} + \text{noise}_{j,t}$

user-nn

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• $\hat{\theta}_{i,t,\text{user-NN}}^{(a)} = \frac{\sum_{j \in \text{user-nn}} Y_{j,t}}{\# \text{ user-nn}} = \frac{\sum_{j \in \text{user-nn}} \theta_{j,t}^{(a)} + \text{noise}_{j,t}}{\# \text{ user-nn}}$



 $= \frac{\sum_{j \in \text{user-nn}} u_j}{\text{# user-nn}} v_t + \text{avg. noise}_t$

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 $\hat{\mathcal{U}}_i$

• $|u_i v_t - \hat{\theta}_{i,t,\text{user-NN}}^{(a)}| \le |u_i v_t - \hat{u}_i v_t| + |\text{avg. noise}_t| = O(|u_i - \hat{u}_i|)$

 $= \frac{\sum_{j \in user-nn} u_j}{\text{# user-nn}} v_t + \text{avg. noise}_t$

Simple case: Estimate $\theta_{i,t}^{(a)} \triangleq f^{(a)}(u_i^{(a)}, v_t^{(a)}) = u_i v_t$





• $|u_i v_t - \hat{\theta}_{i,t,\text{user-NN}}^{(a)}| \le |u_i v_t - \hat{u}_i v_t| + |\text{avg. noise}_t| = O(|u_i - \hat{u}_i|)$ noise at *t* correlated with user neighbors (sequential policy)

 $= \frac{\sum_{j \in user-nn} u_j}{\text{# user-nn}} v_t + \text{avg. noise}_t$



Simple case: Estimate $\theta_{i,t}^{(a)} \triangleq f^{(a)}(u_i^{(a)}, v_t^{(a)}) = u_i v_t$





 \hat{u}_i

• $|u_i v_t - \hat{\theta}_{i,t,\text{user-NN}}^{(a)}| \le |u_i v_t - \hat{u}_i v_t| + |\text{avg. noise}_t| = O(|u_i - \hat{u}_i|)$



noise at *t* correlated with user noise at a construction of the sequential policy)

Martingale concentration, **new sandwich argument** for nn



Simple case: Estimate $\theta_{i,t}^{(a)} \triangleq f^{(a)}(u_i^{(a)}, v_t^{(a)}) = u_i v_t$





• $|u_i v_t - \hat{\theta}_{i,t,\text{user-NN}}^{(a)}| \le |u_i v_t - \hat{u}_i v_t| + |\text{avg. noise}_t| = O(|u_i - \hat{u}_i|)$

• $|u_i v_t - \hat{\theta}_{i,t,\text{time-NN}}^{(a)}| \le |u_i v_t - u_i \hat{v}_t| + |\text{avg. noise}_i| = O(|v_t - \hat{v}_t|)$

 $= \frac{\sum_{j \in user-nn} u_j}{\text{# user-nn}} v_t + \text{avg. noise}_t$

noise at *t* correlated with user neighbors (sequential policy)

Martingale concentration, **new sandwich argument** for nn



• Plug-in principle: $|u_i v_t - \hat{u}_i \hat{v}_t| \le |u_i v_t - \hat{u}_i v_t| + |\hat{u}_i v_t - \hat{u}_i \hat{v}_t|$

 $= O(|u_i - \hat{u}_i| + |v_t - \hat{v}_t|)$

• Plug-in principle: $|u_i v_t - \hat{u}_i \hat{v}_t| \leq |u_i v_t - \hat{u}_i \hat{v}_t|$

• Convert + to X: $|u_i v_t - ??| = O(|u_i - \hat{u}_i| \times |v_t - \hat{v}_t|)$

$$|u_i v_t - \hat{u}_i v_t| + |\hat{u}_i v_t - \hat{u}_i \hat{v}_t|$$

$$O(|u_i - \hat{u}_i| + |v_t - \hat{v}_t|)$$

 \approx

 \approx

• **Plug-in** principle: $|u_i v_t - \hat{u}_i \hat{v}_t| \le |u_i v_t - \hat{u}_i \hat{v}_t| \le |u_i$

• Convert + to \times : $|u_i v_t - ??| = 0$

$$|u_i v_t - \hat{u}_i v_t| + |\hat{u}_i v_t - \hat{u}_i \hat{v}_t|$$

$$O(|u_i - \hat{u}_i| + |v_t - \hat{v}_t|)$$

$$\max\{|\hat{u}_i - u_i|, |v_t - \hat{v}_t|\}$$

$$O(|u_i - \hat{u}_i| \times |v_t - \hat{v}_t|)$$

$$\min\{|\hat{u}_{i} - u_{i}|, |v_{t} - \hat{v}_{t}|\}$$





 $u_i v_t - ?? = (u_i - \hat{u}_i) \times (v_t - \hat{v}_t)$







 $u_{\vec{x}}v_t - ?? = (u_i - \hat{u}_i) \times (v_t - \hat{v}_t)$

 $= \underline{y}_i \hat{v}_t - \hat{u}_i v_t - u_i \hat{v}_t + \hat{u}_i \hat{v}_t$

 $?? = \hat{u}_i v_t + u_i \hat{v}_t - \hat{u}_i \hat{v}_t$









$$(u_i - \hat{u}_i) \times (v_t - \hat{v}_t)$$

$$= \underbrace{u_i v_t}_{i} - \hat{u}_i v_t - u_i \hat{v}_t + \hat{u}_i \hat{v}_t$$

$$\hat{u}_i v_t + u_i \hat{v}_t - \hat{u}_i \hat{v}_t$$

$$Y_{j,t} + Y_{i,t'} - Y_{j,t'}$$

$$\eta_{t,t'}^{(a)} \leq \eta, \ \rho_{t,t'}^{(a)} \leq \eta'$$



This is our improved nearest neighbors estimator!





 $\mathbf{1}_{i,t,j,t'} = \mathbf{1}(\rho_{i,j}^{(a)} \le \eta, \ \rho_{t,t'}^{(a)} \le \eta', A_{j,t} = A_{i,t'} = A_{j,t'} = a)$

 $u_{\vec{x}}v_t - ?? = (u_i - \hat{u}_i) \times (v_t - \hat{v}_t)$

$$= \underline{u}_i v_t - \hat{u}_i v_t - u_i \hat{v}_t + \hat{u}_i \hat{v}_t$$





This is our improved nearest neighbors estimator!





DR-NN error \approx user-NN error \times time-NN error min{user-NN error, time-NN error}

 $u_t v_t - ?? = (u_i - \hat{u}_i) \times (v_t - \hat{v}_t)$

$$= \underline{u}_i v_t - \hat{u}_i v_t - u_i \hat{v}_t + \hat{u}_i \hat{v}_t$$

$$\hat{u}_i v_t + u_i \hat{v}_t - \hat{u}_i \hat{v}_t$$



This is our improved nearest neighbors estimator!





Doubly robust to heterogeneity in user factors & time factors

Double robustness, double machine learning...

 $u_{t}v_{t} - ?? = (u_{i} - \hat{u}_{i}) \times (v_{t} - \hat{v}_{t})$

$$= \underline{u}_i v_t - \hat{u}_i v_t - u_i \hat{v}_t + \hat{u}_i \hat{v}_t$$

DR-NN error \approx user-NN error \times time-NN error min{user-NN error, time-NN error}

[... Cassel+ '77, Robinson '88, Särndal+ '89, Robins+ '94, '95, '08, '09, Newey+ '94, '18, Bickel+ '98, van der Laan+ '03, Lunceford+ '04, Davidian+ '05, Li+ '11, Jiang+ '15, Chernozhukov+ '18, Hirshberg+ '18, Diaz '19, Arkhangelsky+ '21, Dorn+ '21 ...]



Simulation results

Simulation results

Uniform latent factors on $[-0.5, 0.5]^4$, Gaussian noise, pooled ε -greedy policy ($\varepsilon = 0.5$)
Simulation results

Uniform latent factors on $[-0.5, 0.5]^4$, Gaussian noise, pooled ε -greedy policy ($\varepsilon = 0.5$)



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Simulation results







Personalized HeartSteps results

Treatments assigned with Thompson sampling independently for 91 users for 90 days, 5 times a day





Personalized HeartSteps results

Treatments assigned with Thompson sampling independently for 91 users for 90 days, 5 times a day



DR-NN error \approx **min** { user-NN error, time-NN error }





Treatments assigned with Thompson sampling independently for 91 users for 90 days, 5 times a day



Personalized HeartSteps results 5....

DR-NN error \approx **min** { user-NN error, time-NN error }



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Part 1 summary: Sample-efficient inference with non-parametric factor models



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Part 1 summary: Sample-efficient inference with non-parametric factor models

 \checkmark Efficient estimators: Doubly robust-NN with $\tilde{O}(T^{-1/2})$ error

Future: Settings with contexts and covariates

- \checkmark Inference in sequential experiments: User-NN with $\tilde{O}(T^{-1/4})$ error

 - ✓ time-NN error
 ✓ min{user-NN error, time-NN error} DR-NN error \approx user-NN error \times time-NN error





1. Use **real data** to infer decision's effect



Talk overview



1. Use **real data** to infer decision's effect



2. Use simulated data to predict decision's effect







Basic unit





Cardiology

Sub-component







Basic unit



Aerospace





Self-driving



Sub-component













Basic unit

(



Aerospace





Self-driving



System Sub-component • • • Human-robot Built environment interaction (city planning)

Plant design



Cell model





Tissue

Heart model







Cell model





Tissue

Heart model







Cell model





[Augustin+'16, Colman'19, Riabiz+'21, Niederer+'21]

Tissue

Heart model



Dysregulation of calcium signaling in heart cells can cause lethal arrhythmias





Cell model





- Task: Simulate multi-scale digital twin models of heart for personalized **predictions** of dysregulation's effect on a patient's heartbeat

[Augustin+'16, Colman'19, Riabiz+'21, Niederer+'21]

Tissue

Heart model



Dysregulation of calcium signaling in heart cells can cause lethal arrhythmias









- Task: Simulate multi-scale digital twin models of heart for personalized **predictions** of dysregulation's effect on a patient's heartbeat
 - measurements via Bayesian inference and posterior sampling

[Augustin+'16, Colman'19, Riabiz+'21, Niederer+'21]

Tissue

Heart model



Dysregulation of calcium signaling in heart cells can cause lethal arrhythmias

1. Estimate cell-model parameters with uncertainty quantification with single cell





Cell model





- Dysregulation of calcium signaling in heart cells can cause lethal arrhythmias
- Task: Simulate multi-scale digital twin models of heart for personalized predictions of dysregulation's effect on a patient's heartbeat
 - measurements via Bayesian inference and posterior sampling
 - Monte Carlo integration

[Augustin+'16, Colman'19, Riabiz+'21, Niederer+'21]

Tissue

Heart model



1. Estimate cell-model parameters with uncertainty quantification with single cell

2. Propagate cell-model uncertainty to whole-heart model via simulations and





Impact of calcium signaling dysregulation on heartbeat— Two-stage inferential pipeline









Heart model f





Impact of calcium signaling dysregulation on heartbeat— Two-stage inferential pipeline







1. Random sampling via MCMC $X_1, ..., X_T \sim \mathbb{P}^*$ (posterior in \mathbb{R}^{38})



Heart model f





Impact of calcium signaling dysregulation on heartbeat— **Two-stage inferential pipeline**







(posterior in \mathbb{R}^{38})







	2. L	Incerta	ainty
	C	Carlo ir	nteg
***	F	$\mathbb{D}^{\star}f \triangleq$	$\int f(X)$











1. Random sampling via MCMC $X_1, \ldots, X_T \sim \mathbb{P}^*$ (posterior in \mathbb{R}^{38})

• $T = 10^6$ to explore \mathbb{P}^* well





2. Uncertainty propagation via Monte Carlo integration (mean, variance,..) $\mathbb{P}^{\star} f \triangleq \int f(X) d\mathbb{P}^{\star}(X) \approx \frac{1}{T} \sum_{i=1}^{T} f(X_i)$











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- $T = 10^6$ to explore \mathbb{P}^* well
- Time to run **MCMC** ~ 2 CPU weeks





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|--|

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<u>Single</u> f simulation ~ <u>4 CPU weeks</u>









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|--|

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- Single f simulation ~ <u>4 CPU weeks</u>
- Time to compute **sample mean** ~ 4 Million CPU weeks











1. Random sampling via MCMC $X_1, ..., X_T \sim \mathbb{P}^*$ (posterior in \mathbb{R}^{38})

- $T = 10^6$ to explore \mathbb{P}^* well
- Time to run MCMC
 ~ 2 CPU weeks
- How to make MCMC computationally faster?





Heart model f

- 2. Uncertainty propagation via Monte Carlo integration (mean, variance,..) $\mathbb{P}^{\star}f \triangleq \int f(X)d\mathbb{P}^{\star}(X) \approx \frac{1}{T} \sum_{i=1}^{T} f(X_i)$
 - <u>Single</u> f simulation ~ <u>4 CPU weeks</u>
 - Time to compute sample mean
 ~ 4 Million CPU weeks
 - How to make integration computationally feasible?





Part 2 overview: Computationally-efficient integration for high-dimensional models







1. Random sampling via MCMC $X_1, ..., X_T \sim \mathbb{P}^*$ (posterior in \mathbb{R}^{38})

- $T = 10^6$ to explore \mathbb{P}^* well
- Time to run MCMC
 ~ 2 CPU weeks
- How to make MCMC computationally faster?







- 2. Uncertainty propagation via Monte Carlo integration (mean, variance,..) $\mathbb{P}^{\star}f \triangleq \int f(X)d\mathbb{P}^{\star}(X) \approx \frac{1}{T} \sum_{i=1}^{T} f(X_i)$
 - <u>Single</u> f simulation ~ <u>4 CPU weeks</u>
 - Time to compute sample mean
 ~ 4 Million CPU weeks
- This talk
- How to make integration computationally feasible?





TID or MCMC points

 X_1, \dots, X_T $\mathbb{P}_T f \triangleq \frac{\sum_{i=1}^T f(X_i)}{T}$



Compress

TID or MCMC points

 X_1, \dots, X_T $\mathbb{P}_T f \triangleq \frac{\sum_{i=1}^T f(X_i)}{T}$

s output points (coreset)



s (fewer) function evaluations



TID or MCMC points

$$X_1, \dots, X_T$$
$$\mathbb{P}_T f \triangleq \frac{\sum_{i=1}^T f(X_i)}{T}$$

Compress

$|\mathbb{P}^{\star}f - \mathbb{P}_T f| = \Theta(T^{-1/2})$

s output points (coreset)



s (fewer) function evaluations



TIID or MCMC points

Compress

$$\mathbb{P}_T f \triangleq \frac{\sum_{i=1}^T f(X_i)}{T}$$

 $\left| \mathbb{P}^{\star} f - \mathbb{P}_{T} f \right| = \Theta(T^{-1/2})$

 X_1, \ldots, X_T

Standard thinning

(take every *T*/*s*-th point)

or iid thinning/ uniform **sub-sampling** s output points (coreset)





TID or MCMC points a million \rightarrow a thousand

$|\mathbb{P}^{\star}f - \mathbb{P}_T f| = \Theta(T^{-1/2})$ Standard thinning







What is the best error we can hope for?

 $T^{1/2}$ output points **T**ID or MCMC points a million \rightarrow a thousand

 $|\mathbb{P}^* f - \mathbb{P}_T f| = \Theta(T^{-1/2}) \qquad \text{Standard thinning} \qquad |\mathbb{P}^* f - \mathbb{P}_{out} f| = \Theta(T^{-1/4})$




What is the best error we can hope for?

 $T^{1/2}$ output points TID or MCMC points a million \rightarrow a thousand



 $\Omega(T^{-1/2})$ minimax lower bound

- If output = $T^{1/2}$ points
- If input = $T \prod points$ (any estimator)

[Tolstikhin+ '17, Philips+ '20]























Prior strategies for efficient integration

T IID or MCMC points a million \rightarrow a thousand

 $|\mathbb{P}^{\star}f - \mathbb{P}_T f| = \Theta(T^{-1/2}) \qquad \text{Standard thinning} \qquad |\mathbb{P}^{\star}f - \mathbb{P}_{out}f| = \Theta(T^{-1/4})$

 $\Omega(T^{-1/2})$ minimax lower bound

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Prior strategies for efficient integration

 $T^{1/2}$ output points TID or MCMC points a million \rightarrow a thousand

Standard thinning

$|\mathbb{P}^{\star}f - \mathbb{P}_{T}f| = \Theta(T^{-1/2})$

Special \mathbb{P}^{\star}

-Uniform on $[0,1]^d$ -Bounded support & special function class

$\Omega(T^{-1/2})$ minimax lower bound







Prior strategies for efficient integration

TIID or MCMC points a million \rightarrow a thousand

$|\mathbb{P}^{\star}f - \mathbb{P}_T f| = \Theta(T^{-1/2})$ Standard thinning

Special \mathbb{P}^{\star}

-Uniform on $[0,1]^d$ -Bounded support & special function class

function class

 $\Omega(T^{-1/2})$ minimax lower bound

 $T^{1/2}$ output points







T IID or MCMC points a million \rightarrow a thousand

$$|\mathbb{P}^{\star}f - \mathbb{P}_T f| = \Theta(T^{-1/2})$$

$\Omega(T^{-1/2})$ minimax lower bound





A new practical & provably near-optimal procedure

TID or MCMC points a million \rightarrow a thousand



 $\Omega(T^{-1/2})$ minimax lower bound

 $T^{1/2}$ output points

$|\mathbb{P}^{\star}f - \mathbb{P}_T f| = \Theta(T^{-1/2}) \qquad \text{Standard thinning} \qquad |\mathbb{P}^{\star}f - \mathbb{P}_{out}f| = \Theta(T^{-1/4})$





Visual comparison on P*

64 iid input points



Standard thinning





Visual comparison on P*

64 iid input points



Standard thinning







Namely, over the unit ball of a reproducing kernel Hilbert space (RKHS)

 $\sup |\mathbb{P}^{\star}f - \mathbb{P}_{out}f|$ $\|f\|_{k} \le 1$



Namely, over the unit ball of a reproducing kernel Hilbert space (RKHS)

 $\sup \left| \mathbb{P}^{\star} f - \mathbb{P}_{out} f \right|$ $\|f\|_{k} \le 1$

• Parameterized by a reproducing kernel k any symmetric ($\mathbf{k}(x, y) = \mathbf{k}(y, x)$) and positive semidefinite function



Bspline

Inverse multiquadric



Namely, over the unit ball of a reproducing kernel Hilbert space (RKHS)

 $\sup |\mathbb{P}^{\star}f - \mathbb{P}_{out}f|$ $\|f\|_{k} \le 1$

• Parameterized by a reproducing kernel **k** any symmetric ($\mathbf{k}(x, y) = \mathbf{k}(y, x)$) and positive semidefinite function



- Metrizes convergence in distribution for popular infinite-dimensional k



Inverse multiquadric



Main result: A high probability bound for generic \mathbb{P}^{\star} and k



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Informal theorem: [Dwivedi and Mackey'21, '22 and Dwivedi-Shetty-Mackey '22] Kernel thinning uses $O(T \log^3 T)$ kernel evaluations to output $T^{1/2}$ points, that with high probability satisfy



Main result: A high probability bound for generic \mathbb{P}^* and k

Informal theorem: [Dwivedi and Mackey'21, '22 and Dwivedi-Shetty-Mackey '22] Kernel thinning uses $O(T \log^3 T)$ kernel evaluations to output $T^{1/2}$ points, that with high probability satisfy

•
$$|\mathbb{P}^{\star}f - \mathbb{P}_{out}f| \lesssim \sqrt{\frac{\log T}{T}} \cdot ||f||_{\mathbf{k}} \sqrt{||\mathbf{k}|}$$

when $|\mathbb{P}^{\star}f - \mathbb{P}_Tf| \lesssim T^{-1/2}$

$\|_{\infty}$ for a fixed f in the RKHS of **k** (any kernel)

•A near-quadratic gain over $T^{-1/4}$ standard thinning error





Main result: A high probability bound for generic \mathbb{P}^* and k

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when $|\mathbb{P}^{\star}f - \mathbb{P}_T f| \lesssim T^{-1/2}$

•
$$\sup_{\|f\|_{\mathbf{k}} \le 1} |\mathbb{P}^* f - \mathbb{P}_{out} f| \lesssim \sqrt{\frac{\log^{d/2+1} T}{T}}$$

$$\lesssim \sqrt{\frac{\log^{d+1} T}{T}}$$

 $\|_{\infty}$ for a fixed f in the RKHS of **k** (any kernel)

- Sub-gaussian \mathbb{P}^{\star} and \mathbf{k} on \mathbb{R}^{d} (Gaussian)

Sub-exponential \mathbb{P}^* and \mathbf{k} on \mathbb{R}^d (Matérn)

•A near-quadratic gain over $T^{-1/4}$ standard thinning error • Matches minimax lower bounds $T^{-1/2}$ up to log factors







Kernel thinning





Kernel thinning \equiv Recursive halving via kernel evaluations







Kernel halving $v_1, v_2, \dots, v_T \rightarrow \text{Kernel}$ halving $\rightarrow v'_1, v'_2, \dots, v'_{T/2}$

$$\frac{\sum_{i=1}^{T} v_i}{T} - \frac{\sum_{i=1}^{T/2} v'_i}{T/2} = \text{small}$$







points X_1, X_2, \dots, X_T \leftarrow Kernel \leftarrow functions in RKHS v_1, v_2, \dots, v_T





$$v_1, v_2, \dots, v_T \rightarrow$$
 Kernel
halving $\rightarrow v'_1, v'_2, \dots, v'_{T/2}$

$$\frac{\sum_{i=1}^{T} v_i}{T} - \frac{\sum_{i=1}^{T/2} v'_i}{T/2} = \text{small}$$

$$\sum_{i=1}^{T} \varepsilon_{i} v_{i} = \sum_{\substack{\varepsilon_{i}=+1}}^{T} v_{i} - \sum_{\substack{\varepsilon_{i}=-1}}^{T} v_{i}$$





$$v_1, v_2, \dots, v_T \rightarrow$$
 Kernel
halving $\rightarrow v'_1, v'_2, \dots, v'_{T/2}$

$$\frac{\sum_{i=1}^{T} v_i}{T} - \frac{\sum_{i=1}^{T/2} v'_i}{T/2} = \text{small}$$







$$v_1, v_2, \dots, v_T \rightarrow$$
 Kernel
halving $\rightarrow v'_1, v'_2, \dots, v'_{T/2}$

$$\frac{\sum_{i=1}^{T} v_i}{T} - \frac{\sum_{i=1}^{T/2} v'_i}{T/2} = \text{small}$$













 $|\Sigma_{i=1}^T \varepsilon_i v_i|$ is small



$\varepsilon_i = \pm 1$ with equal probability

 $|\Sigma_{i=1}^{T} \varepsilon_{i} v_{i}|$ is small



 $\varepsilon_i = \pm 1$ with equal probability

$$\sigma_T^2 = \sigma_{T-1}^2 + v_T^2$$

$$|\Sigma_{i=1}^T \varepsilon_i v_i| = O(\sigma_T) = O(T^{1/2})$$

Standard thinning

 $|\Sigma_{i=1}^T \varepsilon_i v_i|$ is small



 $\varepsilon_i = \pm 1$ with equal probability

$$\sigma_T^2 = \sigma_{T-1}^2 + v_T^2$$

$$|\Sigma_{i=1}^T \varepsilon_i v_i| = O(\sigma_T) = O(T^{1/2})$$

Standard thinning

 $|\Sigma_{i=1}^T \varepsilon_i v_i|$ is small

 ε_i negatively correlated with $\Sigma_{j=1}^{i-1} \varepsilon_j v_j$



 $\varepsilon_i = \pm 1$ with equal probability

$$\sigma_T^2 = \sigma_{T-1}^2 + v_T^2$$

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Standard thinning

 $|\Sigma_{i=1}^T \varepsilon_i v_i|$ is small

 ε_i negatively correlated with $\Sigma_{j=1}^{i-1} \varepsilon_j v_j$

$\sigma_T^2 \leq \beta \sigma_{T-1}^2 + v_T^2 \text{ for } \beta < 1$



 $\varepsilon_i = \pm 1$ with equal probability

$$\sigma_T^2 = \sigma_{T-1}^2 + v_T^2$$

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Standard thinning

 $|\Sigma_{i=1}^T \varepsilon_i v_i|$ is small

 ε_i negatively correlated with $\sum_{j=1}^{i-1} \varepsilon_j v_j$ $\sigma_T^2 \leq \beta \sigma_{T-1}^2 + v_T^2$ for $\beta < 1$ $|\sum_{i=1}^T \varepsilon_i v_i| = O(\sigma_T) = O(\sqrt{\log T})$



 $\varepsilon_i = \pm 1$ with equal probability

$$\sigma_T^2 = \sigma_{T-1}^2 + v_T^2$$

$$|\Sigma_{i=1}^T \varepsilon_i v_i| = O(\sigma_T) = O(T^{1/2})$$

Standard thinning

 $|\Sigma_{i=1}^T \varepsilon_i v_i|$ is small

 ε_i negatively correlated with $\Sigma_{j=1}^{i-1} \varepsilon_j v_j$

$\sigma_T^2 \leq \beta \sigma_{T-1}^2 + v_T^2 \text{ for } \beta < 1$

 $|\Sigma_{i=1}^{T} \varepsilon_{i} v_{i}| = O(\sigma_{T}) = O(\sqrt{\log T})$

Kernel thinning





 $\varepsilon_i = \pm 1$ with equal probability

$$\sigma_T^2 = \sigma_{T-1}^2 + v_T^2$$

$$|\Sigma_{i=1}^T \varepsilon_i v_i| = O(\sigma_T) = O(T^{1/2})$$

Standard thinning

 $|\Sigma_{i=1}^T \varepsilon_i v_i|$ is small

 $\varepsilon_{i} \text{ negatively correlated with } \Sigma_{j=1}^{i-1} \varepsilon_{j} v_{j}$ $\sigma_{T}^{2} \leq \beta \sigma_{T-1}^{2} + v_{T}^{2} \text{ for } \beta < 1$ $|\Sigma_{i=1}^{T} \varepsilon_{i} v_{i}| = O(\sigma_{T}) = O(\sqrt{\log T})$

Kernel thinning

Discrepancy minimization

[.... Spencer '77, Banaszczyk '98, '12, Eldan+ '18, ... Bansal+ '16, '18, '19, '20, **Dwivedi**+ '19, <u>Alweiss+ '21</u>, ...]





Is KT better practically? Gaussian \mathbb{P}^{\star} in \mathbb{R}^d

Output size \sqrt{T}

iid input, Gaussian kernel



Is KT better practically? Gaussian \mathbb{P}^{\star} in \mathbb{R}^d



iid input, Gaussian kernel



Is KT better practically? Gaussian \mathbb{P}^{\star} in \mathbb{R}^d



iid input, Gaussian kernel


Is KT better practically? Gaussian \mathbb{P}^* in \mathbb{R}^d



iid input, Gaussian kernel

Significant gains in d = 100with just 8 output points







KT on MCMC points for \mathbb{P}^{\star} in

[†]Input = 2 MCMC runs on 2 posteriors \mathbb{P}^* , Gaussian kernel

[†MCMC data from Riabiz-Chen-Cockayne-Swietach-Niederer-Mackey-Oates '21]





KT on MCMC points for \mathbb{P}^{\star} in

[†]Input = 2 MCMC runs on 2 posteriors \mathbb{P}^* , Gaussian kernel

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KT on MCMC points for \mathbb{P}^* in

[†]Input = 2 MCMC runs on 2 posteriors \mathbb{P}^* , Gaussian kernel



Standard thinning does well but **KT provides further improvement** & offers **50% computational savings** (each point ~ 4 CPU weeks)

[†MCMC data from Riabiz-Chen-Cockayne-Swietach-Niederer-Mackey-Oates '21]







Kernel thinning: Near-optimal compression in near-linear time





Kernel thinning: Near-optimal compression in near-linear time

python[™] pip install goodpoints

Thin 100k points in 100 dimensions in 10mins















From HeartSteps





Personalized simulations by thinning neighborhoods

From HeartSteps

to HeartBeats









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Quadratic gains via discrepancy minimization







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Data and computation efficient methods for personalized decision-making







Deep dive into personalization by a reinforcement learning algorithm



Dwivedi*-Zhang*-Chhabria-Klasnja-Murphy '23



Data and computation efficient methods for personalized decision-making





Stable discovery of interpretable subgroups in randomized studies via calibration



Dwivedi*-Tan*-Park-Wei-Horgan-Madigan-Yu '20





Deep dive into personalization by a reinforcement learning algorithm



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Data and computation efficient methods for personalized decision-making











































Randomized experiments

Sequential experiments

Model

going forward...

End-to-end pipeline

- design algorithms for multiple objectives

Uncertainty quantification Optimization

Thank you! raazdwivedi.github.io





Propensity-adjusted user nearest neighbors estimator for $\theta_{i,t}^{(a)}$

 $\rho_{i,j}^{(a)} = \frac{\sum_{t'=1}^{T} (Y_{i,t'} - Y_{j,t'})^2 \cdot \mathbf{1}(A_{i,t'} = A_{j,t'} = a)}{\sum_{t'=1}^{T} \mathbf{1}(A_{i,t'} = A_{j,t'} = a)}$

 $\widehat{\theta}_{i,t,\text{user-NN}}^{(a)} = \frac{\sum_{j=1}^{N} Y_{j,t} \cdot \mathbf{1}(\mu)}{\sum_{j=1}^{N} \mathbf{1}(\rho_{i,j}^{(a)})}$

 $Y_{i,t} = \theta_{i,t}^{(A_{i,t})} + \text{noise}_{i,t}$

- Distance between two users *i* and *j* under treatment *a* = squared distance
- between their outcomes averaged over all times when both treated with a

Estimate = Averaged outcome across user neighbors treated with a at time t

$$\rho_{i,j}^{(a)} \leq \eta, A_{j,t} = a)$$

$$a_{j}^{(a)} \leq \eta, A_{j,t} = a$$



Propensity-adjusted user nearest neighbors estimator for $\theta_{i,t}^{(a)}$

 $\rho_{i,j}^{(a)} = \frac{\sum_{t'=1}^{I} (Y_{i,t'} - Y_{j,t'})^2 \cdot \mathbf{1}(A_{i,t'} = A_{j,t'} = a)}{\sum_{t'=1}^{T} \mathbf{1}(A_{i,t'} = A_{j,t'} = a)}$

Estimate = Averaged outcome across user neighbors treated with a at time t

 $\widehat{\theta}^{(a)} = \underbrace{\sum_{j=1}^{N} Y_{j,t} \cdot \mathbf{1}}_{I(t)}$ $\widehat{\boldsymbol{\theta}}_{i,t,\text{user-NN}}^{(a)} = \frac{\sigma}{\sum_{j=1}^{N} \mathbf{1}(\rho_{i,j}^{(a)} \le \eta, A_{j,t} = a)}$

 $Y_{i,t} = \theta_{i,t}^{(A_{i,t})} + \text{noise}_{i,t}$

Distance between two users *i* and *j* under treatment *a* = squared distance between their outcomes averaged over all times when both treated with a

$$\sum_{t'=1}^{T} (Y_{i,t'} - Y_{j,t'})^2 \cdot \frac{\mathbf{1}(A_{i,t'} = A_{j,t'} = a)}{\mathbb{P}(\mathbf{1}(A_{i,t'} = A_{j,t'} = a) \mid \mathcal{F}_{t'})}$$

$$\sum_{t'=1}^{T} \frac{\mathbf{1}(A_{i,t'} = A_{j,t'} = a)}{\mathbb{P}(\mathbf{1}(A_{i,t'} = A_{j,t'} = a) \mid \mathcal{F}_{t'})}$$

$$\rho_{i,j}^{(a)} \leq \eta, A_{j,t} = a)$$



Propensity-adjusted user nearest neighbors estimator for $\theta_{it}^{(a)}$

 $\rho_{i,j}^{(a)} = \frac{\sum_{t'=1}^{T} (Y_{i,t'} - Y_{j,t'})^2 \cdot \mathbf{1}(A_{i,t'} = A_{j,t'} = a)}{\sum_{t'=1}^{T} \mathbf{1}(A_{i,t'} = A_{j,t'} = a)}$

Estimate = Averaged outcome across user neighbors treated with a at time t

 $\widehat{\theta}_{i}^{(a)} = \underbrace{\sum_{j=1}^{N} Y_{j,t} \cdot \mathbf{1}(f)}_{i}$ $\sigma_{i,t,user-NN} = --$

 $Y_{i,t} = \theta_{i,t}^{(A_{i,t})} + \text{noise}_{i,t}$

Distance between two users *i* and *j* under treatment *a* = squared distance between their outcomes averaged over all times when both treated with a

$$\sum_{t'=1}^{T} (Y_{i,t'} - Y_{j,t'})^2 \cdot \frac{\mathbf{1}(A_{i,t'} = A_{j,t'} = a)}{\mathbb{P}(\mathbf{1}(A_{i,t'} = A_{j,t'} = a) \mid \mathcal{F}_{t'})} \\ \sum_{t'=1}^{T} \frac{\mathbf{1}(A_{i,t'} = A_{j,t'} = a)}{\mathbb{P}(\mathbf{1}(A_{i,t'} = A_{j,t'} = a) \mid \mathcal{F}_{t'})}$$

$$\rho_{i,j}^{(a)} \leq \eta, A_{j,t} = a)$$

 $\sum_{i=1}^{N} \mathbf{1}(\rho_{i,j}^{(a)} \le \eta, A_{j,t} = a)$

Allows non-iid time factors albeit with worse variance





IID signs



$$\varepsilon_i = \begin{cases} +1 \text{ w.p. } 0.5 \\ -1 \text{ w.p. } 0.5 \end{cases}$$

•
$$\sigma_T^2 \triangleq \operatorname{Var}(\Sigma_{i=1}^{T-1} \varepsilon_i v_i + \varepsilon_T v_T)$$

$$= \operatorname{Var}(\sum_{i=1}^{T-1} \varepsilon_i v_i) + \operatorname{Var}(\varepsilon_T v_T) + 2\mathbb{E}[\varepsilon_T \psi_{T-1} v_T]$$

$$= \sigma_{T-1}^2 + v_T^2 = \sum_{i=1}^{T} v_i^2 = O(T)$$

• $|\Sigma_{i=1}^T \varepsilon_i v_i| = O(\sigma_T) = O(T^{1/2})$

Standard thinning

Correlated signs VS

 $|\Sigma_{i=1}^T \varepsilon_i v_i|$ is small

$$\varepsilon_{i} = \begin{cases} +1 \text{ w.p. } 0.5(1 - \psi_{i-1}v_{i}/a) \\ -1 \text{ w.p. } 0.5(1 + \psi_{i-1}v_{i}/a) \end{cases}$$
$$\varepsilon_{i} = \sqrt{2} \text{ Var}(\Sigma_{i=1}^{T-1}\varepsilon_{i}v_{i}) + \sqrt{2} \text{ Var}(\varepsilon_{T}v_{T}) - 2\mathbb{E}[\psi_{T-1}^{2}] \\ \leq \beta \sigma_{T-1}^{2} + v_{T}^{2} \text{ for some } \beta < 1^{\dagger} \\ \leq a/(1 - \beta) \leq \log T \end{cases}$$
$$\varepsilon_{i} = \sqrt{2} \text{ Var}(1 - \beta) \leq \log T$$
$$\varepsilon_{i} = \sqrt{2} \text{ Var}(1 - \beta) \leq \log T$$
$$\varepsilon_{i} = \sqrt{2} \text{ Var}(1 - \beta) \leq \log T$$

By building on self-balancing walk of Alweiss+ '21





Non-linear double/squared robustness

- $f(u,0) = f(0,0) + f'_u(0,0)u +$
- f(0,v) = f(0,0) + f(0,0) +
- $f(u, v) = f(0,0) + f'_u(0,0)u + f'_v(0,0)$

$$+f''_{uu}(\tilde{u},0)u^2$$

 $+f'_{\nu}(0,0)\nu + f''_{\nu\nu}(0,\hat{\nu})\nu^2$

$$v + [u, v] \nabla^2 f(\tilde{u}, \tilde{v}) \begin{bmatrix} u \\ v \end{bmatrix}$$

• $f(u,0) + f(0,v) - f(u,v) = f(0,0) + O((u+v)^2) \Longrightarrow \text{Error} = \max\{u^2, v^2\}$



Additional results for Personalized Heartsteps



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Additional results for Personalized Heartsteps





Additional results for Personalized Heartsteps



