

Instability, Computational Efficiency, and Statistical Accuracy

Nhat Ho

University of Texas, Austin

Joint work with Raaz Dwivedi, Koulik Khamaru, Martin J. Wainwright,
Michael I. Jordan, Bin Yu

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Talk outline

- 1 Challenges with optimization methods in parametric statistical models
- 2 Population to sample analysis framework
 - Contraction of population operator
 - Stability of sample operator
- 3 Convergence of optimization methods under different settings of operators
 - Stable and fast operators
 - Stable and slow operators
 - Unstable and fast operators
 - Unstable and slow operators

Main story

Unstable optimization algorithms can be preferred to stable algorithms in some statistical settings.

Parametric statistical models

- Given a random sample of size n

$$X_1, \dots, X_n \sim f_{\theta^*}(x)$$

- Known:** family of distributions $\{f_{\theta}(x), \theta \in \Theta\}$
- Unknown:** θ^*

Estimation methods

- Standard approaches to estimate θ^* include M-estimators, methods of moments, etc.
- **Challenge:** f_θ is generally non-convex function and optimal solutions from these approaches do not admit closed-forms
- **Solution:** Optimization algorithms are used to approximate θ^*

Fundamental questions

- Under what conditions does an optimization algorithm achieve a statistically optimal rate?
- When is an unstable optimization algorithm, such as Newton's method, preferred to a stable algorithm, such as gradient descent method?

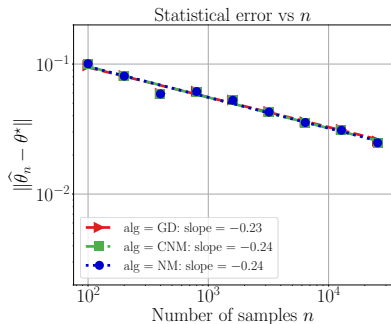
First example: Non-linear regression model

- $\{(X_i, Y_i)\}_{i=1}^n$ are generated from a noisy non-linear regression model of the form

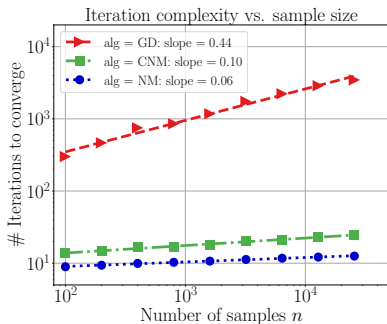
$$Y_i = g(X_i^\top \theta^*) + \xi_i, \quad \text{for } i = 1, \dots, n.$$

- ξ_i is a zero-mean noise variable with variance σ^2
- $g(t) = t^2$ for $t \in \mathbb{R}$

Behavior of optimization algorithms



(a)



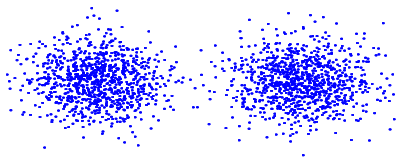
(b)

The behavior of gradient descent (GD), cubic-regularized Newton's method (CNM), and the Newton's method (NM) for the regression model when $\theta^* = 0$.

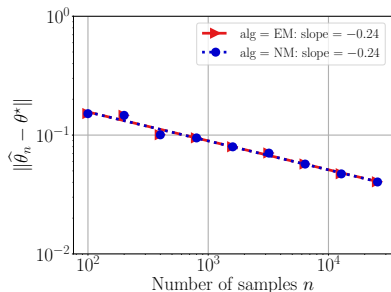
- All the algorithms achieve optimal statistical rates $n^{-1/4}$
- Newton's method takes least number of steps ($\approx \log(n)$) while gradient descent takes significantly larger number of steps ($\approx \sqrt{n}$)

Second example: Mixture model

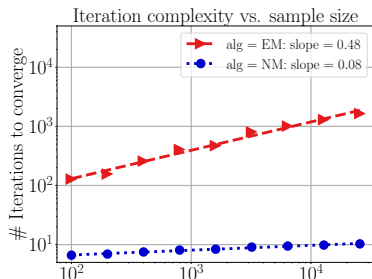
- Two-component Gaussian mixtures:
 - ▶ True model: $\frac{1}{2}\mathcal{N}(-\theta^*, \mathbb{I}_d) + \frac{1}{2}\mathcal{N}(\theta^*, \mathbb{I}_d)$
 - ▶ Fitted model: $\frac{1}{2}\mathcal{N}(-\theta, \mathbb{I}_d) + \frac{1}{2}\mathcal{N}(\theta, \mathbb{I}_d)$



Behavior of optimization algorithms



(a)



(b)

The behavior of EM algorithm and the Newton's method (NM) for the mixture model when $\theta^* = 0$.

- EM and Newton's method achieve optimal statistical rates $n^{-1/4}$
- Newton's method takes $\approx \log(n)$ steps to converge while EM algorithm takes significantly larger number of steps ($\approx \sqrt{n}$)

General framework

- F_n : the empirical operator
 - ▶ Example: $F_n(\theta) = \theta - \eta \nabla f_n(\theta)$ where f_n is sample log-likelihood function
- F : the population operator
 - ▶ Example: $F(\theta) = \theta - \eta \nabla f(\theta)$ where f is population log-likelihood function, i.e., the limit of f_n when $n \rightarrow \infty$
- θ^* : fixed point of F , i.e., $F(\theta^*) = \theta^*$
- $\theta_n^{t+1} = F_n(\theta_n^t)$ for $t = 1, 2, \dots$

Question

Under which conditions, $\{\theta_n^t\}$ approaches a suitably defined neighborhood of θ^* ?

Population to sample analysis

- Triangle inequality:

$$\|\theta_n^{t+1} - \theta^*\| = \|F_n(\theta_n^t) - \theta^*\| \leq \underbrace{\|F(\theta_n^t) - \theta^*\|}_A + \underbrace{\|F_n(\theta_n^t) - F(\theta_n^t)\|}_B$$

- A : Contraction of population operator
- B : Deviation between sample and population operators

Contraction of population operator F

There are two types of contractions:

- **Fast convergence:** For $\kappa \in (0, 1)$, F is FAST(κ)-convergent if

$$\|F^t(\theta_0) - \theta^*\| \leq \kappa^t \|\theta_0 - \theta^*\| \quad \text{for all } t = 1, 2, \dots$$

- **Slow convergence:** For $\beta > 0$, F is SLOW(β)-convergent if

$$\|F^t(\theta_0) - \theta^*\| \leq \frac{c}{t^\beta} \quad \text{for all } t = 1, 2, \dots$$

Example: Fast versus slow convergence

- $\min_{\theta} f(\theta) = \frac{\theta^{2p}}{2p}$ for some $p \geq 1$
- Gradient descent algorithm:

$$F(\theta) = \theta - \eta \nabla f(\theta) = \theta(1 - \eta \theta^{2p-2})$$

- When $p = 1$, F is FAST(κ)-convergent algorithm with $\kappa = 1 - \eta$
- When $p \geq 2$, F is SLOW(β)-convergent with $\beta = \frac{1}{2p-2}$

Deviation between sample and population operators

There are two types of deviations:

- **Stability condition:** For $\gamma \geq 0$, F_n is STA(γ)-stable with noise $\varepsilon(\cdot)$ if

$$\mathbb{P}\left[\sup_{\theta \in \text{Ball}(\theta^*, r)} \|F_n(\theta) - F(\theta)\| \lesssim \min\{r^\gamma \varepsilon(n, \delta), r\}\right] \geq 1 - \delta$$

for any $r > 0$

- **Instability condition:** For $\gamma < 0$, F_n is UNS(γ)-unstable with noise $\varepsilon(\cdot)$ if

$$\mathbb{P}\left[\sup_{\theta \in \text{Annulus}(\theta^*, r, \rho_{\text{out}})} \|F_n(\theta) - F(\theta)\| \leq \varepsilon(n, \delta) \max\left\{\frac{1}{r^{|\gamma|}}, \rho_{\text{out}}\right\}\right] \geq 1 - \delta$$

for any radius $r \geq \rho_{\text{in}}$.

Example of stable condition

- $\min_{\theta} f_n(\theta) = \frac{\theta^4}{4} + \frac{w}{2\sqrt{n}}\theta^2$ where $w \sim N(0, \sigma^2)$
- Gradient descent:
 - ▶ Sample operator: $F_n(\theta) = \theta \left(1 - \eta\theta^2 - \eta\frac{w}{\sqrt{n}}\right)$
 - ▶ Population operator: $F(\theta) = \theta(1 - \eta\theta^2)$
- With probability $1 - \delta$,

$$|F_n(\theta) - F(\theta)| = \eta|\theta| \frac{|w|}{\sqrt{n}} \lesssim |\theta| \sqrt{\frac{\log(1/\delta)}{n}}$$

$\implies F_n$ is STA(γ)-stable with $\gamma = 1$ and noise $\varepsilon(n, \delta) = \sqrt{\log(1/\delta)/n}$

Example of unstable condition

- $\min_{\theta} f_n(\theta) = \frac{\theta^4}{4} + \frac{w}{2\sqrt{n}}\theta^2$ where $w \sim N(0, \sigma^2)$
- Newton's method:
 - ▶ Sample operator: $F_n(\theta) = \theta - \frac{\theta^3 + w\theta/\sqrt{n}}{3\theta^2 + w/\sqrt{n}}$
 - ▶ Population operator: $F(\theta) = \theta - \frac{\theta^3}{3\theta^2}$
- With probability $1 - \delta$, when $|\theta| \gtrsim \left(\frac{\log(1/\delta)}{n}\right)^{1/4}$:

$$|F_n(\theta) - F(\theta)| \lesssim \frac{1}{|\theta|} \sqrt{\frac{\log(1/\delta)}{n}}$$

$\implies F_n$ is UNS(γ)-unstable with parameter $\gamma = -1$ and noise $\varepsilon(n, \delta) = \sqrt{\log(1/\delta)/n}$

General theory: Stable and fast operators

- The operator F is **FAST**(κ)-convergent
- The empirical operator F_n is **STA**(γ)-stable with noise $\varepsilon(n, \delta)$ for some $\gamma \geq 0$

Theorem 1 (Balakrishnan et al., 2017)

Under suitable initialization, the sequence $\theta_n^{t+1} = F_n(\theta_n^t)$ satisfies

$$\|\theta_n^t - \theta^*\| \lesssim \varepsilon(n, \delta) \quad \text{when } t \gtrsim \log(1/\varepsilon(n, \delta)).$$

Furthermore, this bound is tight.

Example of stable and fast operators

- $\{(X_i, Y_i)\}_{i=1}^n$ are generated from a noisy non-linear regression model of the form

$$Y_i = (X_i \theta^*)^2 + \xi_i, \quad \text{for } i = 1, \dots, n.$$

where $|\theta^*| \gg \gg 1$

- $\xi_i \sim \mathcal{N}(0, 1)$ and $X_i \sim \mathcal{N}(0, 1)$
- We use gradient descent method (GD) to the least-squares loss

Example of stable and fast operators

- Population GD operator F^{GD} is $\text{FAST}(\frac{1}{2})$ -convergent
- Sample GD operator F_n^{GD} is $\text{STA}(1)$ -stable with noise $\varepsilon(n, \delta) = \sqrt{\frac{\log^4(n/\delta)}{n}}$
- Under suitable initialization, the sequence $\theta_n^{t+1} = F_n^{\text{GD}}(\theta_n^t)$ satisfies

$$|\theta_n^t - \theta^*| \lesssim n^{-1/2} \quad \text{when } t \gtrsim \log(n)$$

General theory: Stable and slow operators

- The population operator F is 1-Lipschitz and is $\text{SLOW}(\beta)$ -convergent
- The empirical operator F_n is $\text{STA}(\gamma)$ -stable for some $\gamma \in [0, (1 + \beta)^{-1})$

Theorem 2

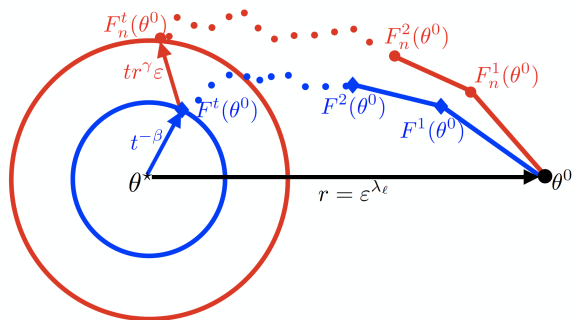
Under suitable initialization, the sequence $\theta_n^{t+1} = F_n(\theta_n^t)$ satisfies

$$\|\theta_n^t - \theta^*\| \lesssim [\varepsilon(n, \delta)]^{\frac{\beta}{1+\beta-\gamma\beta}} \quad \text{when } t \gtrsim \varepsilon(n, \delta)^{-\frac{1}{1+\beta-\gamma\beta}}.$$

Furthermore, this bound is tight.

Outline of proof: Epoch-based argument

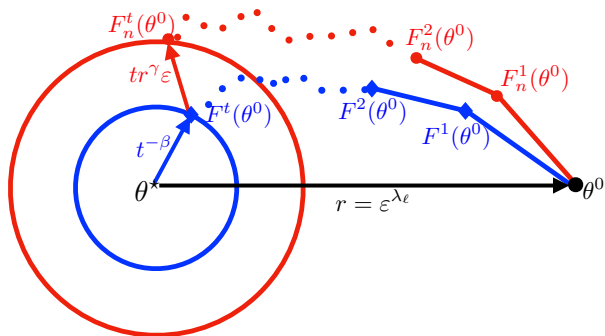
- Assume θ^0 the starting point for epoch ℓ and $r = \|\theta^* - \theta^0\| = \varepsilon(n, \delta)^{\lambda_\ell}$
- Slow convergence of population iterates: $\|F^t(\theta^0) - \theta^*\| \lesssim t^{-\beta}$
- Stability of sample operator: $\|F_n^t(\theta^0) - F^t(\theta^0)\| \lesssim t \cdot r^\gamma \cdot \varepsilon$



- Goal:** At the end of epoch ℓ , we want to find suitable t and $\lambda_{\ell+1}$ such that $\|F_n^t(\theta^0) - \theta^*\| \lesssim \varepsilon^{\lambda_{\ell+1}}$

Outline of proof: Epoch-based argument

Proof sketch for epoch ℓ



$$\|F_n^t(\theta^0) - \theta^*\| \leq \|F_n^t(\theta^0) - F^t(\theta^0)\| + \|F^t(\theta^0) - \theta^*\| \leq tr^{\gamma}\epsilon + \frac{1}{t^\beta} = t\epsilon^{\gamma\lambda_\ell+1} + \frac{1}{t^\beta} \underset{\text{min over } t}{\gtrsim} \epsilon^{\lambda_{\ell+1}}$$

where $\lambda_{\ell+1} = \nu\lambda_\ell + \nu' \implies \lim_{\ell \rightarrow \infty} \lambda_\ell = \nu_\star = \frac{\beta}{1 + \beta - \gamma\beta}$, and $\nu_\star - \lambda_\ell \leq \alpha$ for all $\ell \geq \mathcal{O}(\log(1/\alpha))$

Example of stable and slow operators

- $\{(X_i, Y_i)\}_{i=1}^n$ are generated from a noisy non-linear regression model of the form

$$Y_i = (X_i \theta^*)^2 + \xi_i, \quad \text{for } i = 1, \dots, n$$

where $\theta^* = 0$

- $\xi_i \sim \mathcal{N}(0, 1)$ and $X_i \sim \mathcal{N}(0, 1)$
- We apply gradient descent method (GD) to the least-squares loss

Example of stable and slow operators

- Population GD operator:

$$F^{\text{GD}}(\theta) = \theta [1 - 6\eta\theta^2]$$

$\implies F^{\text{GD}}$ is $\text{SLOW}(\frac{1}{2})$ -convergent as $\eta \in (0, \frac{1}{6}]$

- Sample GD operator:

$$F_n^{\text{GD}}(\theta) = \theta - \eta \left(\frac{2}{n} \sum_{i=1}^n X_i^4 \theta^3 - \frac{2}{n} \sum_{i=1}^n Y_i X_i^2 \theta \right)$$

$\implies F_n^{\text{GD}}$ is $\text{STA}(1)$ -stable with noise $\varepsilon(n, \delta) = \sqrt{\frac{\log^4(n/\delta)}{n}}$

- Under suitable initialization, the sequence $\theta_n^{t+1} = F_n^{\text{GD}}(\theta_n^t)$ satisfies

$$|\theta_n^t - \theta^*| \lesssim n^{-1/4} \quad \text{when } t \gtrsim \sqrt{n}$$

General theory: Unstable and fast operators

- The population operator F is **FAST**(κ)-convergent
- The empirical operator F_n is **UNS**(γ)-unstable over the annulus $\mathbb{A}(\theta^*, \tilde{\rho}_n, \rho)$ for some $\gamma < 0$

Theorem 3

Under suitable initialization, the sequence $\theta_n^{t+1} = F_n(\theta_n^t)$ satisfies

$$\min_{k \in \{0, 1, \dots, t\}} \|\theta_n^k - \theta^*\| \lesssim \max \left\{ [\varepsilon(n, \delta)]^{\frac{1}{1+|\gamma|}}, \tilde{\rho}_n \right\} \quad \text{when } t \gtrsim \log(1/\varepsilon(n, \delta)).$$

Furthermore, this bound is tight.

Outline of proof

- Assume that $\|\theta_n^t - \theta^*\| > [\varepsilon(n, \delta)]^{\frac{1}{1+|\gamma|}}$ for all $t \lesssim \log(1/\varepsilon(n, \delta))$
- As F is **FAST**(κ)-convergent and F_n is **UNS**(γ)-unstable,

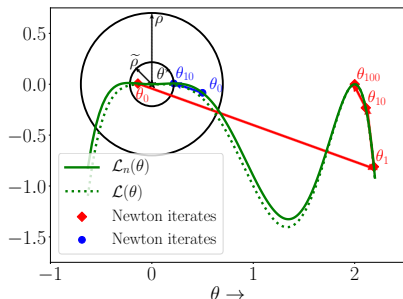
$$\begin{aligned}\|\theta_n^{t+1} - \theta^*\| &\leq \|F_n(\theta_n^t) - F(\theta_n^t)\| + \|F(\theta_n^t) - \theta^*\| \\ &\leq \varepsilon(n, \delta) \max \left\{ \frac{1}{[\varepsilon(n, \delta)]^{\frac{|\gamma|}{1+|\gamma|}}}, \rho \right\} + \kappa \cdot \|\theta_n^t - \theta^*\| \\ &\dots \\ &\leq \varepsilon(n, \delta) \max \left\{ \frac{1}{[\varepsilon(n, \delta)]^{\frac{|\gamma|}{1+|\gamma|}}}, \rho \right\} (1 + \kappa + \dots + \kappa^{t-1}) \\ &\quad + \kappa^t \cdot \|\theta_n^0 - \theta^*\| \\ &\lesssim [\varepsilon(n, \delta)]^{\frac{1}{1+|\gamma|}},\end{aligned}$$

when $t \lesssim \log(1/\varepsilon(n, \delta))$

Necessity of the minimum

- We consider the following example:

$$\mathcal{L}(\theta) = -\theta^4(\theta - 2)^2 \quad \text{and} \quad \mathcal{L}_n(\theta) = -\left(\theta^4 - \frac{\theta^2}{\sqrt{n}}\right)(\theta - 2)^2$$



- When the initialization is too close to θ^* (red diamonds), Newton's iterates jump far away from θ^* and converge to another fixed point
- When the initialization is in $\mathbb{A}(\theta^*, \tilde{\rho}, \rho)$, the Newton iterates (blue circles) do not leave this annulus and converge to a small neighborhood of θ^*

Additional regularity condition to remove the minimum

- The population operator F is **FAST**(κ)-convergent
- The empirical operator F_n is **UNS**(γ)-unstable over the annulus $\mathbb{A}(\theta^*, \tilde{\rho}_n, \rho)$ for some $\gamma < 0$
- There exists a constant C such that the sequence $\theta_n^t = F_n^t(\theta_n^0)$ satisfies:

$$\|\theta_n^{t+1} - \theta^*\| \leq C\tilde{\rho} \quad \text{whenever} \quad \|\theta_n^t - \theta^*\| \leq \tilde{\rho},$$

$$\text{where } \tilde{\rho} = \max \left\{ [\varepsilon(n, \delta)]^{\frac{1}{1+|\gamma|}}, \tilde{\rho}_n \right\}$$

Proposition 4

Under suitable initialization, the sequence $\theta_n^{t+1} = F_n(\theta_n^t)$ satisfies

$$\|\theta_n^t - \theta^*\| \lesssim \max \left\{ [\varepsilon(n, \delta)]^{\frac{1}{1+|\gamma|}}, \tilde{\rho}_n \right\} \quad \text{when } t \gtrsim \log(1/\varepsilon(n, \delta)).$$

Furthermore, this bound is tight.

Example of unstable and fast operators

- $\{(X_i, Y_i)\}_{i=1}^n$ are generated from a noisy non-linear regression model of the form

$$Y_i = (X_i \theta^*)^2 + \xi_i, \quad \text{for } i = 1, \dots, n$$

where $\theta^* = 0$

- $\xi_i \sim \mathcal{N}(0, 1)$ and $X_i \sim \mathcal{N}(0, 1)$
- We apply Newton's method (NM) to the least-squares loss

Example of unstable and slow operators

- Population NM operator:

$$F^{\text{NM}}(\theta) = \theta - \frac{\theta^3}{3\theta^2} = \frac{2}{3}\theta$$

$\implies F^{\text{NM}}$ is FAST($\frac{2}{3}$)-convergent

- Sample NM operator:

$$F_n^{\text{GD}}(\theta) = \theta - \frac{\left(\frac{1}{n} \sum_{i=1}^n X_i^4\right) \theta^3 - \left(\frac{1}{n} \sum_{i=1}^n Y_i X_i^2\right) \theta}{\left(\frac{3}{n} \sum_{i=1}^n X_i^4\right) \theta^2 - \frac{1}{n} \sum_{i=1}^n Y_i X_i^2}$$

$\implies F_n^{\text{NM}}$ is UNS(-1)-unstable over the annulus $\mathbb{A}(\theta^*, \tilde{\rho}_n, 1)$ with $\tilde{\rho}_n \asymp \log(n/\delta)/n^{1/4}$

Example of unstable and slow operators

- F^{NM} is $\text{FAST}(\frac{2}{3})$ -convergent
- F_n^{NM} is $\text{UNS}(-1)$ -unstable over the annulus $\mathbb{A}(\theta^*, \tilde{\rho}_n, 1)$ with $\tilde{\rho}_n \asymp \log(n/\delta)/n^{1/4}$
- Additional regularity condition:

$$|F_n^{\text{NM}}(\theta)| \geq |\theta_n^*|$$

for all $|\theta| \in [|\theta_n^*|, 1]$ where θ_n^* is global solution of least-squares loss

- Under suitable initialization, the sequence $\theta_n^{t+1} = F_n^{\text{NM}}(\theta_n^t)$ satisfies

$$|\theta_n^t - \theta^*| \lesssim n^{-1/4} \quad \text{when } t \gtrsim \log(n)$$

General theory: Unstable and slow operators

- The population operator F is 1-Lipschitz and is **SLOW**(β)-convergent
- The empirical operator F_n is **UNS**(γ)-unstable over the annulus $\mathbb{A}(\theta^*, \tilde{\rho}_n, \rho)$ for some $\gamma < 0$

Theorem 5

Under suitable initialization, the sequence $\theta_n^{t+1} = F_n(\theta_n^t)$ satisfies

$$\min_{k \in \{0, 1, \dots, t\}} \|\theta_n^k - \theta^*\| \lesssim \max \left\{ [\varepsilon(n, \delta)]^{\frac{\beta}{1+\beta-\gamma\beta}}, \tilde{\rho}_n \right\} \quad \text{when } t \gtrsim \varepsilon(n, \delta)^{-\frac{1}{1+\beta}}.$$

Furthermore, this bound is tight.

Outline of proof

- $\nu_\star = \frac{\beta}{1+\beta-\gamma\beta}$
- Assume that $\|\theta_n^t - \theta^\star\| > \max\{[\varepsilon(n, \delta)]^{\nu_\star}, \tilde{\rho}_n\}$ for all $t \lesssim \varepsilon(n, \delta)^{-\frac{1}{1+\beta}}$
- As F is **SLOW**(β)-convergent and F_n is **UNS**(γ)-unstable,

$$\begin{aligned}\|\theta_n^{t+1} - \theta^\star\| &\leq \frac{1}{t^\beta} + t \cdot \frac{\varepsilon(n, \delta)}{[\varepsilon(n, \delta)]^{\nu_\star|\gamma|}} \\ &\lesssim [\varepsilon(n, \delta)]^{\nu_\star},\end{aligned}$$

when $t \lesssim \varepsilon(n, \delta)^{-\frac{1}{1+\beta}}$

Example of unstable and slow operators

- $\{(X_i, Y_i)\}_{i=1}^n$ are generated from a noisy non-linear regression model of the form

$$Y_i = (X_i \theta^*)^2 + \xi_i, \quad \text{for } i = 1, \dots, n$$

where $\theta^* = 0$

- $\xi_i \sim \mathcal{N}(0, 1)$ and $X_i \sim \mathcal{N}(0, 1)$
- We apply cubic-regularized Newton's method (CNM) to the least-squares loss

Example of unstable and slow operators

- $\tilde{\mathcal{L}}$ and $\tilde{\mathcal{L}}_n$ are population and sample least-square losses
- Population CNM operator:

$$\begin{aligned} F^{\text{CNM}}(\theta) &= \arg \min_{y \in \mathbb{R}} \left\{ \tilde{\mathcal{L}}'(\theta)(y - \theta) + \frac{1}{2} \tilde{\mathcal{L}}''(\theta)(y - \theta)^2 + L |y - \theta|^3 \right\} \\ &= \theta - \frac{\frac{2}{3} \theta^3}{\theta^2 + \sqrt{\theta^4 + \frac{2}{3} \theta^3}} \end{aligned}$$

$\implies F^{\text{CNM}}$ is SLOW(2)-convergent

- Sample CNM operator:

$$F_n^{\text{CNM}}(\theta) = \arg \min_{y \in \mathbb{R}} \left\{ \tilde{\mathcal{L}}'_n(\theta)(y - \theta) + \frac{1}{2} \tilde{\mathcal{L}}''_n(\theta)(y - \theta)^2 + L |y - \theta|^3 \right\}$$

$\implies F_n^{\text{CNM}}$ is UNS($-\frac{1}{2}$)-unstable over the annulus $\mathbb{A}(\theta^*, \tilde{\rho}_n, 1)$ with $\tilde{\rho}_n \asymp \log(n/\delta)/n^{1/4}$

Example of unstable and slow operators

- F^{CNM} is SLOW(2)-convergent
- F_n^{CNM} is UNS($-\frac{1}{2}$)-unstable over the annulus $\mathbb{A}(\theta^*, \tilde{\rho}_n, 1)$ with $\tilde{\rho}_n \asymp \log(n/\delta)/n^{1/4}$
- Additional regularity condition:

$$|F_n^{\text{CNM}}(\theta)| \geq |\theta_n^*|$$

for all $|\theta| \in [|\theta_n^*|, 1]$ where θ_n^* is global solution of least-squares loss

- Under suitable initialization, the sequence $\theta_n^{t+1} = F_n^{\text{CNM}}(\theta_n^t)$ satisfies

$$|\theta_n^t - \theta^*| \lesssim n^{-1/4} \quad \text{when } t \gtrsim n^{1/6}$$

Summary of results

Operator Properties	Optimization Rate	Stability	Iterations for convergence	Statistical error on convergence
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General expressions

Fast, stable	FAST(κ)	STA(γ)	$\log(1/\varepsilon(n, \delta))$	$\varepsilon(n, \delta)$
Slow, stable	SLOW(β)	STA(γ)	$\varepsilon(n, \delta)^{-\frac{1}{1+\beta-\gamma\beta}}$	$[\varepsilon(n, \delta)]^{\frac{\beta}{1+\beta-\gamma\beta}}$
Fast, unstable	FAST(κ)	UNS(γ)	$\log(1/\varepsilon(n, \delta))$	$[\varepsilon(n, \delta)]^{\frac{1}{1+ \gamma }}$
Slow, unstable	SLOW(β)	UNS(γ)	$[\varepsilon(n, \delta)]^{-\frac{1}{1+\beta}}$	$[\varepsilon(n, \delta)]^{\frac{\beta}{1+\beta+ \gamma \beta}}$

Examples

Fast, stable	$e^{-\kappa t}$	$\frac{r}{\sqrt{n}}$	$\log n$	$n^{-1/2}$
Slow, stable	$\frac{1}{\sqrt{t}}$	$\frac{r}{\sqrt{n}}$	$n^{1/2}$	$n^{-1/4}$
Fast, unstable	$e^{-\kappa t}$	$\frac{1}{r\sqrt{n}}$	$\log n$	$n^{-1/4}$
Slow, unstable	$\frac{1}{t^2}$	$\frac{1}{\sqrt{r}\sqrt{n}}$	$n^{1/6}$	$n^{-1/4}$